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Stochastic conservation laws: Weak-in-time formulation and strong entropy condition [☆]



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ABSTRACT

This article is an attempt to complement some recent developments on conservation laws with stochastic forcing. In a pioneering development, Feng and Nualart [8] have developed the entropy solution theory for such problems and the presence of stochastic forcing necessitates introduction of *strong entropy condition*. However, the authors' formulation of entropy inequalities are weak-in-space but strong-in-time. In the absence of a priori path continuity for the solutions, we take a critical outlook towards this formulation and offer an entropy formulation which is weak-in-time and weak-in-space.

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1. Introduction

Let $(\Omega, P, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0})$ be a filtered probability space which satisfies the usual hypothesis. We are interested in finding an $L^2(\mathbb{R}^d)$ (or an appropriate function space)-valued predictable process $u(t)$ which satisfies the stochastic partial differential equation

$$du(t, x) + \operatorname{div}_x F(u(t, x)) dt = \sigma(x, u(t, x)) dW(t) \quad t > 0, x \in \mathbb{R}^d, \quad (1.1)$$

with the initial condition

$$u(0, x) = u_0(x), \quad x \in \mathbb{R}^d. \quad (1.2)$$

In the above, $W(t)$ is an one-dimensional standard Brownian motion, $F : \mathbb{R} \rightarrow \mathbb{R}^d$ is the flux function, and $\sigma(x, u)$ is a real valued function defined on the domain $\mathbb{R}^d \times \mathbb{R}$.

In the case where $\sigma = 0$, Eq. (1.1) becomes a standard scalar conservation law with spatial dimension d . It is well-known for conservation laws that solutions (that are obtained by method of characteristics) may develop discontinuities in finite time even when the initial data is smooth. In other words, the problem (1.1)–(1.2) does not have smooth solutions in general, even when the right hand side is zero. In this situation one has to invoke the notion of weak solutions, but the issues would persist as there could be infinitely many weak solutions to a given problem. It was a huge step forward for analytical understanding of scalar conservation laws when Kruzkov came up with his idea of entropy solutions. Kruzkov's notion of entropy condition correctly isolates the physically relevant solution in a unique way, and there is a large body of literature (see [9,4] and references therein) that has emerged on this subject.

Stochastic conservation laws is a relatively new area of pursuit. Only recently the conservation laws with stochastic forcing have attracted the attention of many authors [8,12,10,5,18,3,6], and resulted in significant momentum in the theoretical development of such problems. As its deterministic counterpart, it is required to have a weak formulation coupled with an entropy criterion to establish the wellposedness for such problems. An equation of type (1.1) could be interpreted as the equation that describes conservation of physical quantities that are subjected to random force fields modeled by diffusion noise. One of the early works in this direction was [10], where one dimensional stochastic balance laws were studied where σ is independent of x . The authors employed the splitting method to construct approximate solutions, and the approximations were shown to converge to a weak (possibly non-unique) solution. At around the same time, Khanin et al. [11] published a very influential article describing some statistical properties of Burgers' equations with stochastic forcing. When the noise term on the right hand side is of additive nature i.e. $\sigma \equiv \sigma(t, x)$, J.U. Kim [12] extended Kruzkov's entropy formulation and established the wellposedness for one dimensional problems under the assumption that $\sigma \in C((0, \infty) : W_x^{1,\infty})$ and has compact support. The straightforward adaptation of the deterministic entropy inequalities fails to capture the noise–noise interaction, and

the standard mechanism to derive the L^1 -contraction principle does not apply for general σ . This issue was finally resolved by Feng and Nualart [8] with the introduction of the notion of *strong entropy* solution. In [8], the authors established the uniqueness of strong entropy solution in L^p -framework for several space dimensions. The existence, however, was restricted to one space dimension. We also refer to the recent articles by Debussche and Vovelle [5] and by Chen et al. [3] for the existence in the multi-dimensional case. In [5], the authors obtain the existence via kinetic formulation. In [3], the authors use the BV solution framework. In this paper, we offer a weaker entropy formulation for (1.1) and establish wellposedness in the L^p -framework. In addition, we refer to [19,17,16,15,14,13,7,2] for additional details relevant to the topic.

In our view, the article [8] by Feng and Nualart is no less than a milestone of the subject and presents a comprehensive theory of entropy solutions for stochastic conservation laws. We draw our primary motivation from [8], but take a critical outlook to the approach and raise a few objections to some of the methods and offer an alternative which we perceive as better suited to the problem. The ordinary entropy inequalities in the stochastic case do not fully capture the noise–noise interactions and it may not be possible to replicate Kruzkov’s approach to get the L^1 -contraction principle. This issue is resolved by Feng and Nualart by introducing an additional condition called *strong entropy condition*. However, the entropy inequalities in [8] could be described as weak in space but strong in time. Moreover, the strong entropy condition is related to this formulation and reflects the strong-in-time picture. This formulation easily leads to the L^1 contraction principle, and uniqueness for such formulation naturally follows. However, the question of existence becomes much more subtle. As its deterministic counterpart, the existence is settled via vanishing viscosity method in [8] and this is where our viewpoint deviates from that of Feng and Nualart [8]. The proof of existence in [8] requires the vanishing viscosity approximates to converge *for all* time points and the authors have made attempts to justify the convergence for all time points. However, a careful analysis reveals that convergence is established for *almost every* time points. This puts a question mark against the validity of the results in [8]. The nature of compactness of vanishing viscosity approximates finds a perfect match with the entropy formulation which is weak both in time and space, and which would coincide with entropy formulation of Feng and Nualart [8] if the solution process had continuous sample paths. In [8], the authors make an attempt to establish path-continuity for the vanishing viscosity limit but there are flaws in the proof. We have added a separate section in this article where we explain these flaws and describe the implications in details. With this apparent inconsistencies in mind, we find it necessary that entropy inequalities are formulated weak both in time and space, and the strong entropy condition has to be accordingly specified to capture noise–noise interaction. In this article we set out to exactly do that.

The rest of the paper is organized as follows. In the next section, we describe the technical framework, define the notion of strong entropy solution for (1.1)–(1.2) and state the main theorems. In Section 3, we establish the uniqueness of strong entropy solution of (1.1)–(1.2) by deriving the L^1 contraction property. In Section 4, we briefly

discuss the wellposedness of vanishing viscosity approximation of (1.1) and establish the existence of entropy solution for (1.1)–(1.2). In Section 5, we show that the vanishing viscosity solution is indeed a strong entropy solution. Finally, in the last section we describe the issues related to the path continuity of vanishing viscosity limit and its implications. We close this section with a description of the notations and symbols and the list of assumptions.

By C , K , etc., we mean various constants which may change from line to line. The Euclidean norm on any \mathbb{R}^d -type space is denoted by $|\cdot|$. Furthermore, let $\Pi_T = (0, T) \times \mathbb{R}^d$. In the rest of the paper, the following assumptions hold:

(A.1) For every $k = 1, 2, \dots, d$, the functions $F_k(s) \in C^2(\mathbb{R})$, and $F_k(s)$, $F'_k(s)$ and $F''_k(s)$ have at most polynomial growth in s .

(A.2) There exists a positive constant $C > 0$ such that

$$|\sigma(y, v) - \sigma(x, u)| \leq C(|u - v| + |x - y|).$$

(A.3) There exists a nonnegative function $g \in L^\infty(\mathbb{R}^d) \cap L^2(\mathbb{R}^d)$ such that

$$|\sigma(x, u)| \leq g(x)(1 + |u|).$$

(A.4) The set $\{r \in \mathbb{R} : F''(r) \neq 0\}$ is dense in \mathbb{R} .

2. Technical framework and statements of the main results

The notion of entropy solution is built around the so-called entropy flux pairs. We begin this section with the definition of entropy flux pairs.

Definition 2.1 (*Entropy flux pair*). (β, ζ) is called an entropy flux pair if $\beta \in C^2(\mathbb{R})$ and $\beta \geq 0$, and $\zeta = (\zeta_1, \zeta_2, \dots, \zeta_d) : \mathbb{R} \mapsto \mathbb{R}^d$ is a vector field satisfying

$$\zeta'(r) = \beta'(r)F'(r).$$

An entropy flux pair (β, ζ) is called convex if $\beta''(s) \geq 0$.

As in the deterministic case, the primary motivation behind the notion of entropy solution comes from parabolic regularization. However, it requires considerable amount of work (cf. [8]) to show that perturbation by small diffusion will indeed regularize the solutions. To proceed, we assume that u is a smooth predictable solution of the parabolic perturbation of (1.1), i.e. u satisfies

$$du(t, x) + \operatorname{div}_x F(u(t, x)) dt = \sigma(x, u(t, x)) dW(t) + \varepsilon \Delta u(t, x) dt, \quad (2.1)$$

where $\varepsilon > 0$ is a small positive number. As compared to the deterministic case, we need to replace the deterministic chain rule for derivatives by Itô chain rule to derive the

entropy inequalities. Let (β, ζ) be a convex entropy flux pair. Then, by Itô formula, we have

$$\begin{aligned} & d\beta(u(t, x)) + \operatorname{div}_x \zeta(u(t, x)) \, dt \\ &= \sigma(x, u(t, x))\beta'(u(t, x)) \, dW(t) + \frac{1}{2}\sigma^2(x, u(t, x))\beta''(u(t, x)) \, dt \\ &+ (\varepsilon\Delta_{xx}\beta(u(t, x)) - \varepsilon\beta''(u(t, x))|\nabla_x u(t, x)|^2) \, dt. \end{aligned}$$

For each $0 \leq \psi \in C_c^{1,2}([0, \infty) \times \mathbb{R}^d)$, we apply Itô product rule to obtain

$$\begin{aligned} d(\beta(u(t, x))\psi(t, x)) &= \partial_t \psi(t, x)\beta(u(t, x)) \, dt - \psi(t, x) \operatorname{div}_x \zeta(u(t, x)) \, dt \\ &+ \psi(t, x)\sigma(x, u(t, x))\beta'(u(t, x)) \, dW(t) \\ &+ \frac{1}{2}\psi(t, x)\sigma^2(x, u(t, x))\beta''(u(t, x)) \, dt \\ &+ \psi(t, x)(\varepsilon\Delta_{xx}\beta(u(t, x)) - \varepsilon\beta''(u(t, x))|\nabla_x u(t, x)|^2) \, dt. \end{aligned}$$

It is to be kept in mind that β is nonnegative and convex and ψ is nonnegative. Therefore, for every $T > 0$, we have

$$\begin{aligned} 0 &\leq \langle \beta(u(T, \cdot)), \psi(T, \cdot) \rangle \\ &\leq \langle \beta(u(0, \cdot)), \psi(0, \cdot) \rangle + \int_0^T \langle \zeta(u(r, \cdot)), \nabla_x \psi(r, \cdot) \rangle \, dr \\ &+ \int_{(0, T]} \langle \beta(u(r, \cdot)), \partial_t \psi(r, \cdot) \rangle \, dr + \int_{(0, T]} \langle \sigma(\cdot, u(r, \cdot))\beta'(u(r, \cdot)), \psi(r, \cdot) \rangle \, dW(r) \\ &+ \frac{1}{2} \int_{(0, T]} \langle \sigma^2(\cdot, u(r, \cdot))\beta''(u(r, \cdot)), \psi(r, \cdot) \rangle \, dr + \mathcal{O}(\varepsilon). \end{aligned} \tag{2.2}$$

Both the left-hand and right-hand sides of the inequality are stable under $\varepsilon \rightarrow 0$, provided we have L^p_{loc} type stability of (2.1) as $\varepsilon \rightarrow 0$. The above inequality leads to the entropy inequalities which are weak both in time and space.

Definition 2.2 (*Stochastic entropy solution*). An $L^2(\mathbb{R}^d)$ -valued $\{\mathcal{F}_t : t \geq 0\}$ -predictable stochastic process $u(t) = u(t, x)$ is called a stochastic entropy solution of (1.1) provided (1) for each $T > 0, p = 2, 3, 4, \dots$

$$\sup_{0 \leq t \leq T} E[\|u(t)\|_p^p] < \infty.$$

(2) For $0 \leq \psi \in C_c^{1,2}([0, \infty) \times \mathbb{R}^d)$ and each convex entropy pair (β, ζ) ,

$$\begin{aligned} & \int_{\mathbb{R}^d} \beta(u_0(x)) \psi(0, x) \, dx + \int_{\Pi_T} \beta(u(t, x)) \partial_t \psi(t, x) \, dt \, dx \\ & + \int_{\Pi_T} \zeta(u(t, x)) \cdot \nabla \psi(t, x) \, dt \, dx + \frac{1}{2} \int_{\Pi_T} \sigma^2(x, u(t, x)) \beta''(u(t, x)) \psi(t, x) \, dx \, dt \\ & + \int_0^T \int_{\mathbb{R}^d} \sigma(x, u(t, x)) \beta'(u(t, x)) \psi(t, x) \, dx \, dW(t) \geq 0 \quad P\text{-a.s.} \end{aligned}$$

In the deterministic case, the entropy inequalities lead to the L^1 -contraction principle which implies uniqueness. In the stochastic case, however, the entropy inequalities alone do not seem to give rise to desired L^1 -contraction principle. **Definition 2.2** does not reveal much about the noise–noise interaction when one tries to compare two solutions of the same problem. We refer to [3] for detailed mathematical description of this issue. However, to ensure uniqueness, we need to arrive at a version of so-called *strong entropy condition* which is compatible with the weak-in-time formulation.

Let ρ and ϱ be the standard mollifiers on \mathbb{R} and \mathbb{R}^d respectively such that $\text{supp}(\rho) \subset [-1, 0]$ and $\text{supp}(\varrho) = B_1(0)$. For $\delta > 0$ and $\delta_0 > 0$, let $\rho_{\delta_0}(r) = \frac{1}{\delta_0} \rho(\frac{r}{\delta_0})$ and $\varrho_\delta(x) = \frac{1}{\delta^d} \varrho(\frac{x}{\delta})$. For a nonnegative test function $\psi \in C_c^{1,2}([0, \infty) \times \mathbb{R}^d)$ and two positive constants δ, δ_0 , define

$$\phi_{\delta, \delta_0}(t, x; s, y) = \rho_{\delta_0}(t - s) \varrho_\delta(x - y) \psi(s, y). \tag{2.3}$$

Note that $\rho_{\delta_0}(t - s) \neq 0$ only if $s - \delta_0 \leq t \leq s$, and therefore $\phi_{\delta, \delta_0}(t, x; s, y) = 0$ outside $s - \delta_0 \leq t \leq s$.

Definition 2.3 (*Stochastic strong entropy solution*). An $L^2(\mathbb{R}^d)$ -valued $\{\mathcal{F}_t : t \geq 0\}$ -predictable stochastic process $v(t) = v(t, x)$ is called a stochastic strong entropy solution of (1.1) provided

- (i) it is a stochastic entropy solution.
- (ii) For each $L^2(\mathbb{R}^d)$ -valued $\{\mathcal{F}_t : t \geq 0\}$ -adapted stochastic process $\tilde{u}(t, x)$ satisfying, for $T > 0, p = 2, 3, 4 \dots$

$$\sup_{0 \leq t \leq T} E[\|\tilde{u}(t)\|_p^2] < \infty,$$

and for each $\beta \in C^\infty(\mathbb{R})$ such that β'' and β''' are of compact support and $0 \leq \psi \in C_c^\infty([0, \infty) \times \mathbb{R}^d)$, and

$$h(r, s; v, y) = \int_x \sigma(x, \tilde{u}(r, x)) \beta'(\tilde{u}(r, x) - v) \phi_{\delta, \delta_0}(r, x; s, y) \, dx,$$

where ϕ_{δ, δ_0} is defined by (2.3),

$$\begin{aligned}
 & E \left[\int_0^T \int_y \left[\int_0^T h(r, s; v, y) dW(r) \right]_{v=v(s,y)} dy ds \right] \\
 & \leq -E \left[\int_{\Pi_T} \int_{\Pi_T} \sigma(x, \tilde{u}(r, x)) \sigma(y, v(r, y)) \beta''(\tilde{u}(r, x) - v(r, y)) \right. \\
 & \quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] + A(\delta, \delta_0),
 \end{aligned}$$

where $A(\delta, \delta_0)$ is a function depending on β, ψ such that $A(\delta, \delta_0) \rightarrow 0$ as $\delta_0 \rightarrow 0$.

Remark. The weak-in-time formulation is also manifested in the *strong entropy condition*. In our formulation the function $A(\delta, \delta_0)$ plays a similar role as that of $A(s, t)$ in Feng and Nualart.

The above definition does not say anything explicitly about the entropy solution satisfying the initial condition. However, it satisfies the initial condition in a certain weak sense. We have the following lemma.

Lemma 2.1. Any entropy solution $u(t, x)$ of (1.1) satisfies the initial condition in the following sense: for every nonnegative $\psi \in C_c^2(\mathbb{R}^d)$ such that $\text{supp}(\psi) = K$,

$$\lim_{h \rightarrow 0} E \left[\frac{1}{h} \int_0^h \int_K |u(t, x) - u_0(x)| \psi(x) dx dt \right] = 0.$$

Proof. Since K is of finite measure, it is enough if we instead prove

$$\lim_{h \rightarrow 0} E \left[\frac{1}{h} \int_0^h \int_K |u(t, x) - u_0(x)|^2 \psi(x) dx dt \right] = 0. \tag{2.4}$$

For $\delta \in (0, 1)$, let $K_\delta = \{x : \text{dist}(x, K) \leq \delta\}$. Note that, for any $\delta > 0$,

$$\begin{aligned}
 & E \int_K |u(t, x) - u_0(x)|^2 \psi(x) dx \\
 & \leq 2E \int_{y \in K_\delta} \int_{x \in K} |u(t, x) - u_0(y)|^2 \psi(x) \varrho_\delta(x - y) dx dy \\
 & \quad + 2E \int_{y \in K_\delta} \int_{x \in K} |u_0(y) - u_0(x)|^2 \psi(x) \varrho_\delta(x - y) dx dy
 \end{aligned} \tag{2.5}$$

where $\{\varrho_\delta\}$ is a sequence of mollifiers in \mathbb{R}^d . In other words

$$\begin{aligned}
 & E \frac{1}{h} \int_0^h \int_K |u(t, x) - u_0(x)|^2 \psi(x) \, dx \, dt \\
 & \leq 2E \frac{1}{h} \int_0^h \int_{y \in K_\delta} \int_{x \in K} |u(t, x) - u_0(y)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy \, dt \\
 & \quad + 2E \int_{y \in K_\delta} \int_{x \in K} |u_0(y) - u_0(x)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy. \tag{2.6}
 \end{aligned}$$

Now let $\psi(t, x) = \gamma(t)\psi(x)\varrho_\delta(x - y)$, where $\gamma(t) = \frac{h-t}{h}$ for $0 \leq t \leq h$. Now, let $\beta(u) = (u - u_0(y))^2$ and $\xi(u) = \int_0^u 2(r - u_0(y))F'(r) \, dr = 2 \int_0^u rF'(r) \, dr - 2u_0(y)(F(u) - F(0)) \leq C(1 + |u_0(y)|^2 + |u|^p)$ for some positive integer p . With the above entropy flux pair (β, ξ) , we apply [Definition 2.2](#) and have

$$\begin{aligned}
 & E \frac{1}{h} \int_0^h \int_{y \in K_\delta} \int_{x \in K} |u(t, x) - u_0(y)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy \, dt \\
 & \leq E \int_{y \in K_\delta} \int_{x \in K} |u_0(y) - u_0(x)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy \\
 & \quad + C\delta^{-2} \int_0^h E \int_{y \in K_\delta} \int_{x \in K} (1 + |u(r, x)|^p + |u_0(y)|^2) \, dx \, dy \, dr \\
 & \quad + \frac{C''}{\delta} \int_0^h E \int_{x \in K} \sigma^2(x, u(r, x)) \, dx \, dr.
 \end{aligned}$$

Hence by passing to the limit $h \rightarrow 0$, we have

$$\begin{aligned}
 & \limsup_{h \rightarrow 0} E \frac{1}{h} \int_0^h \int_{y \in K_\delta} \int_{x \in K} |u(t, x) - u_0(y)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy \, dt \\
 & \leq E \int_{y \in K_\delta} \int_{x \in K} |u_0(y) - u_0(x)|^2 \psi(x) \varrho_\delta(x - y) \, dx \, dy. \tag{2.7}
 \end{aligned}$$

We combine [\(2.6\)](#) and [\(2.7\)](#) and obtain

$$\limsup_{h \rightarrow 0} E \frac{1}{h} \int_0^h \int_K |u(t, x) - u_0(x)|^2 \psi(x) \, dx \, dt$$

$$\leq 4E \int_{y \in K_\delta} \int_{x \in K} |u_0(y) - u_0(x)|^2 \psi(x) \varrho_\delta(x - y) dx dy \quad \text{for all } \delta > 0. \tag{2.8}$$

We now simply let $\delta \rightarrow 0$ in the RHS of (2.8) and obtain

$$\limsup_{h \rightarrow 0} E \frac{1}{h} \int_0^h \int_K |u(t, x) - u_0(x)|^2 \psi(x) dx dt \leq 0.$$

Hence (2.4) follows as $\psi \geq 0$. This completes the proof. \square

Next, we describe a special class of entropy functions that plays an important role in the sequel. Let $\beta : \mathbb{R} \rightarrow \mathbb{R}$ be a nonnegative smooth function satisfying

$$\beta(0) = 0, \quad \beta(-r) = \beta(r), \quad \beta'(-r) = -\beta'(r), \quad \beta'' \geq 0,$$

and

$$\beta'(r) = \begin{cases} -1 & \text{when } r \leq -1, \\ \in [-1, 1] & \text{when } |r| < 1, \\ +1 & \text{when } r \geq 1. \end{cases}$$

For any $\epsilon > 0$, define $\beta_\epsilon : \mathbb{R} \rightarrow \mathbb{R}$ by

$$\beta_\epsilon(r) = \epsilon \beta\left(\frac{r}{\epsilon}\right).$$

Then

$$|r| - M_1 \epsilon \leq \beta_\epsilon(r) \leq |r| \quad \text{and} \quad |\beta''_\epsilon(r)| \leq \frac{M_2}{\epsilon} \mathbf{1}_{|r| \leq \epsilon}, \tag{2.9}$$

where

$$M_1 = \sup_{|r| \leq 1} ||r| - \beta(r)|, \quad M_2 = \sup_{|r| \leq 1} |\beta''(r)|.$$

By simply dropping ϵ , for $\beta = \beta_\epsilon$ we define

$$\begin{aligned} F_k^\beta(a, b) &= \int_b^a \beta'(\sigma - b) F'_k(\sigma) d(\sigma), \\ F^\beta(a, b) &= (F_1^\beta(a, b), F_2^\beta(a, b), \dots, F_d^\beta(a, b)), \\ F_k(a, b) &= \text{sign}(a - b) (F_k(a) - F_k(b)), \\ F(a, b) &= (F_1(a, b), F_2(a, b), \dots, F_d(a, b)). \end{aligned}$$

We are now ready to state the main results of this paper.

Theorem 2.2 (Uniqueness). *Let the assumptions (A.1)–(A.3) be true, and that $\bigcap_{p=1,2,\dots} L^p(\mathbb{R}^d)$ -valued and \mathcal{F}_0 -measurable random variable u_0 satisfies*

$$E[\|u_0\|_p^p + \|u_0\|_2^p] < \infty \quad \text{for } p = 1, 2, \dots$$

Suppose that u, v be two stochastic entropy solutions of (1.1) with the same initial condition $u(0) = u_0 = v(0)$, and that at least one of u, v is a strong stochastic entropy solution. Then almost surely $u(t) = v(t)$ for almost every $t \geq 0$.

We further assume that $d = 1$, and state the existence theorem of strong entropy solution.

Theorem 2.3 (Existence). *Let the assumptions (A.1)–(A.4) be true and $d = 1$. Furthermore, $\bigcap_{p=1,2,\dots} L^p(\mathbb{R}^d)$ -valued \mathcal{F}_0 -measurable random variable u_0 satisfies*

$$E[\|u_0\|_p^p + \|u_0\|_2^p] < \infty \quad \text{for } p = 1, 2, \dots$$

Then there exists a strong entropy solution for (1.1)–(1.2).

Remark. In the sequel it is going to be clear that our results are still valid if the noise is of the form $\sum_{i=1}^m \sigma_i(x, u) dW_i(t)$. This is a special case of space–time noise $\int_z \sigma(u, x, z) \partial_t W(t, dz)$ in [8]. This space–time noise structure does have close resemblance with Lévy/pure jump type noise structure $\int_z \tilde{N}(dz, dt)$. From our recent experience of working with conservation laws with Lévy noise, we confidently infer that our results could be extended to the generalized noise structure of [8].

3. Proof of uniqueness

The proof of uniqueness follows a line argument that suitably adapts Kruzkov’s method of doubling the variables to the stochastic case. The central idea of the proof is to analyze the evolution of $\|u(t) - v(t)\|_{L^1(\mathbb{R}^d)}$ as a random quantity, and then arrive at the conclusion that $E(\|u(t) - v(t)\|_{L^1(\mathbb{R}^d)})$ decreases as a function of time. In our context also we use doubling of variables, and approximate $\|u(s) - v(s)\|_{L^1(\mathbb{R}^d)}$ by $\int_0^T \int_{\mathbb{R}^d \times \mathbb{R}^d} \beta(u(t, x) - v(t, y)) \psi(t) \varphi(x, y) dx dy dt$, where $\beta(r)$ is a suitable smooth convex approximation of $|r|$ and $\varphi(x, y)$ is a smooth approximation for $\delta_x(y)$ and $\psi(t)$ is a smooth approximation of $\delta_s(t)$. We will, however, have to handle additional difficulties due to the stochastic forcing.

Let u be a stochastic entropy solution and v be a stochastic strong entropy solution to Eq. (1.1). Let $0 \leq \psi \in C_c^{1,2}([0, \infty) \times \mathbb{R}^d)$ be given and $\beta \equiv \beta_\epsilon$ (as described above). For a fixed real number $k \in \mathbb{R}$, $\beta(\cdot - k)$ is a convex smooth function. Therefore $(\beta(\cdot - k), F^\beta(\cdot, k))$ could be chosen as the corresponding convex entropy flux pair where $F^\beta(a, b)$ is described above. Next, we lay down the entropy inequality for $u(t, x)$ relative to the convex entropy

pair $(\beta(\cdot - k), F^\beta(\cdot, k))$ and substitute k by $v(s, y)$ and integrate with respect to s, y to get

$$\begin{aligned}
 & \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(u_0(x) - v(s, y)) \phi_{\delta, \delta_0}(0, x, s, y) \, dx \, dy \, ds \\
 & + \int_{\Pi_T} \int_{\Pi_T} \beta(u(t, x) - v(s, y)) \partial_t \phi_{\delta, \delta_0} \, dx \, dt \, dy \, ds \\
 & + \int_0^T \int_y \left[\int_0^T h(r, s, ; v, y) dW(r) \right]_{v=v(s, y)} \, dy \, ds \\
 & + \frac{1}{2} \int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(s, y)) \phi_{\delta, \delta_0}(t, x; s, y) \, dx \, dt \, dy \, ds \\
 & + \int_{\Pi_T} \int_{\Pi_T} F^\beta(u(t, x), v(s, y)) \nabla_x \phi_{\delta, \delta_0} \, dx \, dt \, dy \, ds \geq 0, \tag{3.1}
 \end{aligned}$$

where $\Pi_T = [0, T] \times \mathbb{R}^d$ and

$$h(r, s; v, y) = \int_x \sigma(x, u(r, x)) \beta'(u(r, x) - v) \phi_{\delta, \delta_0}(r, x; s, y) \, dx.$$

Similarly, since $v(s, y)$ is also a stochastic entropy solution, by substituting $k = u(t, x)$ and integrating with respect to (t, x) we have

$$\begin{aligned}
 & \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(v_0(y) - u(t, x)) \phi_{\delta, \delta_0}(t, x, 0, y) \, dx \, dy \, dt \\
 & + \int_{\Pi_T} \int_{\Pi_T} \beta(v(s, y) - u(t, x)) \partial_s \phi_{\delta, \delta_0} \, dy \, ds \, dx \, dt \\
 & + \int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma(y, v(s, y)) \beta'(v(s, y) - u(t, x)) \phi_{\delta, \delta_0} \, dy \, dW(s) \, dx \, dt \\
 & + \frac{1}{2} \int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(y, v(s, y)) \beta''(v(s, y) - u(t, x)) \phi_{\delta, \delta_0}(t, x; s, y) \, dy \, ds \, dx \, dt \\
 & + \int_{\Pi_T} \int_{\Pi_T} F^\beta(v(s, y), u(t, x)) \nabla_y \phi_{\delta, \delta_0} \, dx \, dt \, dy \, ds \geq 0 \tag{3.2}
 \end{aligned}$$

Adding the two inequalities (3.1) and (3.2) and using the fact that $\text{supp } \rho_{\delta_0} \subset [-\delta_0, 0]$, we notice that the terms involving $\partial_s \rho_{\delta_0}$ and $\partial_t \rho_{\delta_0}$ cancel each other and we are left with

$$\begin{aligned}
 & \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(u_0(x) - v(s, y)) \psi(s, y) \rho_{\delta_0}(-s) \varrho_{\delta}(x - y) dx dy ds \\
 & + \int_{\Pi_T} \int_{\Pi_T} \beta(v(s, y) - u(t, x)) \partial_s \psi(s, y) \rho_{\delta_0}(t - s) \varrho_{\delta}(x - y) dy ds dx dt \\
 & + \int_{\Pi_T} \int_{\Pi_T} F^{\beta}(v(s, y), u(t, x)) \nabla_y \psi(s, y) \rho_{\delta_0}(t - s) \varrho_{\delta}(x - y) dx dt dy ds \\
 & + \int_{\Pi_T} \int_{\Pi_T} F^{\beta}(u(t, x), v(s, y)) \nabla_x \varrho_{\delta}(x - y) \psi(s, y) \rho_{\delta_0}(t - s) dy ds dx dt \\
 & + \int_{\Pi_T} \int_{\Pi_T} F^{\beta}(v(s, y), u(t, x)) \nabla_y \varrho_{\delta}(x - y) \psi(s, y) \rho_{\delta_0}(t - s) dx dt dy ds \\
 & + \int_0^T \int_y \left[\int_0^T h(r, s, ; v, y) dW(r) \right]_{v=v(s,y)} dy ds \\
 & + \int_{\Pi_T} \int_t^{t+\delta_0} \int_{\mathbb{R}^d} \sigma(y, v(s, y)) \beta'(v(s, y) - u(t, x)) \phi_{\delta, \delta_0}(t, x; s, y) dy dW(s) dx dt \\
 & + \frac{1}{2} \int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(y, v(s, y)) \beta''(v(s, y) - u(t, x)) \phi_{\delta, \delta_0}(t, x; s, y) dy ds dx dt \\
 & + \frac{1}{2} \int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(s, y)) \phi_{\delta, \delta_0}(t, x; s, y) dx dt dy ds \\
 & \geq 0. \tag{3.3}
 \end{aligned}$$

We now take expectation on both sides and use the property of $v(s, y)$ as a strong entropy solution to have

$$\begin{aligned}
 & E \left[\int_{\Pi_T} \int_{\mathbb{R}^d} \beta(u_0(x) - v(s, y)) \psi(s, y) \rho_{\delta_0}(-s) \varrho_{\delta}(x - y) dx dy ds \right] \\
 & + E \left[\int_{\Pi_T} \int_{\Pi_T} \beta(v(s, y) - u(t, x)) \partial_s \psi(s, y) \rho_{\delta_0}(t - s) \varrho_{\delta}(x - y) dy dx dt ds \right] \\
 & + E \left[\int_{\Pi_T} \int_{\Pi_T} F^{\beta}(v(s, y), u(t, x)) \nabla_y \psi(s, y) \rho_{\delta_0}(t - s) \varrho_{\delta}(x - y) dx dt dy ds \right]
 \end{aligned}$$

$$\begin{aligned}
 &+ E \left[\int_{\Pi_T} \int_{\Pi_T} F^\beta(u(t, x), v(s, y)) \nabla_x \varrho_\delta(x - y) \psi(s, y) \rho_{\delta_0}(t - s) dx dy dt ds \right] \\
 &+ E \left[\int_{\Pi_T} \int_{\Pi_T} F^\beta(v(s, y), u(t, x)) \nabla_y \varrho_\delta(x - y) \psi(s, y) \rho_{\delta_0}(t - s) dx dt dy ds \right] \\
 &+ \frac{1}{2} E \left[\int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(s, y)) \phi_{\delta, \delta_0}(t, x; s, y) dx dt dy ds \right] \\
 &+ \frac{1}{2} E \left[\int_{\Pi_T} \int_0^T \int_{\mathbb{R}^d} \sigma^2(y, v(s, y)) \beta''(v(s, y) - u(t, x)) \phi_{\delta, \delta_0}(t, x; s, y) dy ds dx dt \right] \\
 &- E \left[\int_{\Pi_T} \int_{\Pi_T} \sigma(x, u(t, x)) \sigma(y, v(t, y)) \beta''(u(t, x) - v(t, y)) \psi(s, y) \right. \\
 &\quad \left. \times \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dy dx dt ds \right] + A(\delta, \delta_0) \\
 &\equiv I_1 + I_2 + I_3 + I_4 + I_5 + I_6 + I_7 + I_8 + A(\delta, \delta_0) \\
 &\geq 0
 \end{aligned} \tag{3.4}$$

Now, we estimate each of the terms above as $\delta_0, \delta \rightarrow 0$ and $\beta \rightarrow |\cdot|$. We start with I_1 .

Lemma 3.1.

$$\lim_{\delta_0 \rightarrow 0} I_1 = E \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \beta(u_0(x) - v_0(y)) \psi(0, y) \varrho_\delta(x - y) dx dy$$

and

$$\begin{aligned}
 &\lim_{(\varepsilon, \delta) \rightarrow (0, 0)} E \int_{\mathbb{R}^d \times \mathbb{R}^d} \beta_\varepsilon(u_0(x) - v_0(y)) \varrho_\delta(x - y) \psi(0, y) dx dy \\
 &= E \int_{\mathbb{R}^d} |u_0(x) - v_0(x)| \psi(0, x) dx.
 \end{aligned}$$

Proof. The proof is divided into two steps, and in each step, we will justify the passage to the corresponding limit.

Step 1: In this step we consider the passage to the limit as $\delta_0 \rightarrow 0$. Let

$$\mathcal{A}_1 := E \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(u_0(x) - v(s, y)) \psi(s, y) \varrho_\delta(x - y) \rho_{\delta_0}(-s) dx dy ds$$

$$\begin{aligned}
& - E \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \beta(u_0(x) - v_0(y)) \psi(0, y) \varrho_\delta(x - y) dx dy \\
& = E \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(u_0(x) - v(s, y)) [\psi(s, y) - \psi(0, y)] \rho_{\delta_0}(-s) \varrho_\delta(x - y) dx dy ds \\
& \quad + E \int_{\Pi_T} \int_{\mathbb{R}^d} [\beta(u_0(x) - v(s, y)) - \beta(u_0(x) - v_0(y))] \\
& \quad \times \psi(0, y) \varrho_\delta(x - y) \rho_{\delta_0}(-s) dx dy ds.
\end{aligned}$$

Since support $\psi(s, \cdot) \subset K$, we have

$$\begin{aligned}
|\mathcal{A}_1| & \leq \|\psi_t\|_\infty E \int_{\Pi_T} \int_{\mathbb{R}^d} \chi_K(y) \beta(u_0(x) - v(s, y)) s \rho_{\delta_0}(-s) \varrho_\delta(x - y) dx dy ds \\
& \quad + \|\beta'\|_\infty E \int_{\Pi_T} \int_{\mathbb{R}^d} |v(s, y) - v_0(y)| \psi(0, y) \varrho_\delta(x - y) \rho_{\delta_0}(-s) dx dy ds \\
& \leq \|\psi_t\|_\infty \|\beta'\|_\infty \delta_0 E \int_{\Pi_T} \int_{\mathbb{R}^d} \chi_K(y) (|u_0(x) - v(s, y)|) \rho_{\delta_0}(-s) \varrho_\delta(x - y) dx dy ds \\
& \quad + \|\beta'\|_\infty E \int_{\Pi_T} \int_{\mathbb{R}^d} |v(s, y) - v_0(y)| \psi(0, y) \varrho_\delta(x - y) \rho_{\delta_0}(-s) dx dy ds \\
& \leq \|\psi_t\|_\infty \|\beta'\|_\infty \delta_0 E \int_{\Pi_T} \int_{\mathbb{R}^d} \chi_K(y) (|u_0(x) - v(s, y)|) \rho_{\delta_0}(-s) \varrho_\delta(x - y) dx dy ds \\
& \quad + \|\beta'\|_\infty E \int_0^T \int_K \psi(0, y) |v(s, y) - v_0(y)| \rho_{\delta_0}(-s) dy ds \\
& \leq \|\psi_t\|_\infty \|\beta'\|_\infty \delta_0 \left[\|u_0(x)\|_{L^1(\mathbb{R}^d)} + E \int_0^T \int_K |v(s, y)| \rho_{\delta_0}(-s) dy ds \right] \\
& \quad + \|\beta'\|_\infty E \int_0^T \int_K \psi(0, y) |v(s, y) - v_0(y)| \rho_{\delta_0}(-s) dy ds \\
& \leq \|\psi_t\|_\infty \|\beta'\|_\infty \delta_0 \left[\|u_0(x)\|_{L^1(\mathbb{R}^d)} + \sup_{0 \leq s \leq T} E(\|v(s, \cdot)\|_{L_1}) \right] \\
& \quad + C \|\beta'\|_\infty \frac{1}{\delta_0} \int_0^{\delta_0} E \left(\int_K \psi(0, y) |v(r, y) - v_0(y)| dy \right) dr.
\end{aligned}$$

By Lemma 2.1, $\lim_{\delta_0 \rightarrow 0} \frac{1}{\delta_0} \int_0^{\delta_0} E(\int_K \psi(0, y)|v(r, y) - v_0(y)| dy) dr = 0$. Therefore, $\lim_{\delta_0 \rightarrow 0} \mathcal{A}_1 = 0$.

Step 2: In this step, we now establish the second half of the lemma. Note that the sequence $(\beta_\varepsilon)_\varepsilon$ is a sequence of functions that satisfies $|\beta_\varepsilon(r) - |r|| \leq C\varepsilon$ for any $r \in \mathbb{R}$. Therefore

$$\begin{aligned} & \left| E \int_{\mathbb{R}^d \times \mathbb{R}^d} \beta_\varepsilon(u_0(x) - v_0(y)) \varrho_\delta(x - y) \psi(0, y) dx dy - E \int_{\mathbb{R}^d} |u_0(y) - v_0(y)| \psi(0, y) dy \right| \\ & \leq E \int_{\mathbb{R}^d \times \mathbb{R}^d} |\beta_\varepsilon(u_0(x) - v_0(y)) - |u_0(x) - v_0(y)|| \varrho_\delta(x - y) \psi(0, y) dx dy \\ & \quad + E \int_{\mathbb{R}^d \times \mathbb{R}^d} \left| |u_0(x) - v_0(y)| - |u_0(y) - v_0(y)| \right| \varrho_\delta(x - y) \psi(0, y) dx dy \\ & \leq \text{Const}(\psi)\varepsilon + E \int_{\mathbb{R}^d \times \mathbb{R}^d} |u_0(x) - u_0(y)| \varrho_\delta(x - y) \psi(0, y) dx dy \\ & \leq \text{Const}(\psi)\varepsilon + \|\psi\|_\infty E \int_{|z| \leq 1} \int_{\mathbb{R}^d} |u_0(x) - u_0(x + \delta z)| \varrho(z) dx dz. \end{aligned}$$

Note that $\lim_{\delta \downarrow 0} \int_{\mathbb{R}^d} |u_0(x) - u_0(x + \delta z)| dx \rightarrow 0$ for all $\|z\| \leq 1$, therefore by bounded convergence theorem we have $\lim_{\delta \downarrow 0} E \int_{|z| \leq 1} \int_{\mathbb{R}^d} |u_0(x) - u_0(x + \delta z)| \varrho(z) dx dz = 0$. This allows us to pass to the limit $(\varepsilon, \delta) \rightarrow (0, 0)$ in the last line and establish the second part of the claim. \square

Lemma 3.2. *It follows that*

$$\lim_{\delta_0 \rightarrow 0} I_2 = E \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(v(s, y) - u(s, x)) \partial_s \psi(s, y) \varrho_\delta(x - y) dy dx ds$$

and

$$\begin{aligned} & \lim_{(\varepsilon, \delta) \rightarrow (0, 0)} E \left[\int_{\Pi_T} \int_x \beta_\varepsilon(v(s, y) - u(s, x)) \partial_s \psi(s, y) \varrho_\delta(x - y) dx dy ds \right] \\ & = E \left[\int_{\Pi_T} |v(s, x) - u(s, x)| \partial_s \psi(s, x) dx ds \right]. \end{aligned}$$

Proof. As before, the proof is divided into two steps and in each of these steps we will justify the corresponding passage to the limit.

Step 1: Firstly, we consider the passage to the limit as $\delta_0 \rightarrow 0$. For this, let

$$\begin{aligned}
 \mathcal{G}_1 &:= \left| E \int_{\Pi_T} \int_{\Pi_T} \beta(v(s, y) - u(t, x)) \partial_s \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dy ds dx dt \right. \\
 &\quad \left. - E \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(v(s, y) - u(s, x)) \partial_s \psi(s, y) \varrho_\delta(x - y) dy dx ds \right| \\
 &= \left| E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{\Pi_T} \beta(v(s, y) - u(t, x)) \partial_s \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dx dt dy ds \right. \\
 &\quad \left. - E \int_{s=\delta_0}^T \int_0^T \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \beta(v(s, y) - u(s, x)) \partial_s \psi(s, y) \varrho_\delta(x - y) \right. \\
 &\quad \left. \times \rho_{\delta_0}(t - s) dy dx dt ds \right| + \mathcal{O}(\delta_0) \\
 &\leq E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{\Pi_T} |\beta(v(s, y) - u(t, x)) - \beta(v(s, y) - u(s, x))| |\partial_s \psi(s, y)| \\
 &\quad \times \varrho_\delta(x - y) \rho_{\delta_0}(t - s) dx dt dy ds + \mathcal{O}(\delta_0) \\
 \mathcal{G}_1 &\leq C(\beta') \|\partial_s \psi\|_\infty E \left[\int_{s=\delta_0}^T \int_{\Pi_T} |u(s, x) - u(t, x)| \rho_{\delta_0}(t - s) dx dt ds \right] + \mathcal{O}(\delta_0) \\
 &\leq C(\beta') \|\partial_s \psi\|_\infty E \left[\int_{r=0}^1 \int_0^T \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)| \rho_1(-r) dx dt dr \right] + \mathcal{O}(\delta_0).
 \end{aligned}
 \tag{3.5}$$

Note that, $\lim_{\delta_0 \downarrow 0} \int_0^T \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)| dx dt \rightarrow 0$ almost surely for all $r \in [0, 1]$. Therefore, by bounded convergence theorem, $\lim_{\delta_0 \downarrow 0} E[\int_0^T \int_{r=0}^1 \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)| \rho_1(-r) dx dr dt] = 0$, and therefore the first step follows.

Step 2: In this step, we establish the second part of the lemma. For this, let

$$\begin{aligned}
 \mathcal{G}_2(\varepsilon, \delta) &:= \left| E \int_{\Pi_T} \int_{\mathbb{R}^d} \beta(v(s, y) - u(s, x)) \partial_s \psi(s, y) \varrho_\delta(x - y) dx dy ds \right. \\
 &\quad \left. - E \int_{\Pi_T} \int_{\mathbb{R}^d} |v(s, y) - u(s, x)| \partial_s \psi(s, y) \varrho_\delta(x - y) dx dy ds \right|
 \end{aligned}$$

$$\begin{aligned} &\leq \|\partial_s \psi\|_\infty E \int_{\text{supp}(\psi(s,y))} \int_{\mathbb{R}^d} \int_0^T |\beta(v(s,y) - u(s,x)) - |v(s,y) - u(s,x)|| \\ &\quad \times \varrho_\delta(x - y) \, ds \, dx \, dy. \end{aligned}$$

As before, note that the sequence $(\beta_\varepsilon)_\varepsilon$ is a sequence of functions that satisfies

$$|\beta_\varepsilon(r) - |r|| \leq C\varepsilon \quad \text{for any } r \in \mathbb{R},$$

we have

$$\mathcal{G}_2(\varepsilon, \delta) \leq \|\partial_s \psi\|_\infty \varepsilon C(\psi, T). \tag{3.6}$$

Once again, let

$$\begin{aligned} \mathcal{G}_3(\delta) &:= \left| E \int_{\Pi_T} \int_{\mathbb{R}^d} |v(s,y) - u(s,x)| \partial_s \psi(s,y) \varrho_\delta(x - y) \, dx \, dy \, ds \right. \\ &\quad \left. - E \int_0^T \int_{\mathbb{R}^d} |v(s,y) - u(s,y)| \partial_s \psi(s,y) \, dy \, ds \right| \\ &\leq E \int_{\Pi_T} \int_{\mathbb{R}^d} |u(s,y) - u(s,x)| \partial_s \psi(s,y) \varrho_\delta(x - y) \, dx \, dy \, ds \rightarrow 0 \quad \text{as } \delta \rightarrow 0 \\ &\quad \text{(as in Lemma 3.1)}. \end{aligned}$$

Now

$$\begin{aligned} &\left| E \left[\int_{\Pi_T} \int_x \beta_\varepsilon(v(s,y) - u(s,x)) \partial_s \psi(s,y) \varrho_\delta(x - y) \, dx \, dy \, ds \right] \right. \\ &\quad \left. - E \left[\int_{\Pi_T} |v(s,x) - u(s,x)| \partial_s \psi(s,x) \, dx \, ds \right] \right| \\ &\leq \mathcal{G}_2(\varepsilon, \delta) + \mathcal{G}_3(\delta) \leq \|\partial_s \psi\|_\infty C(\psi, T) \varepsilon + \mathcal{G}_3(\delta) \rightarrow 0 \quad \text{as } (\varepsilon, \delta) \rightarrow (0, 0). \end{aligned}$$

Hence the second part follows. \square

Next we estimate the limit of I_3 as $\delta_0 \rightarrow 0$ and $(\varepsilon, \delta) \downarrow (0, 0)$.

Lemma 3.3.

$$\lim_{\delta_0 \rightarrow 0} I_3 = E \int_{\mathbb{R}^d} \int_{\Pi_T} F^\beta(v(s,y), u(s,x)) \nabla_y \psi(s,y) \varrho_\delta(x - y) \, dy \, ds \, dx$$

and

$$\begin{aligned} & \lim_{(\varepsilon, \delta) \rightarrow (0,0)} E \int_{\Pi_T} \int_{\mathbb{R}^d} F^{\beta\varepsilon}(v(s, y), u(s, x)) \nabla_y \psi(s, y) \varrho_\delta(x - y) dx dy ds \\ &= E \left[\int_{\Pi_T} \sum_{k=1}^d \text{sign}(u(s, y) - v(s, y)) (F_k(u(s, y)) - F_k(v(s, y))) \partial_{y_k} \psi(s, y) dy ds \right]. \end{aligned}$$

Proof. The proof is divided into two steps.

Step 1: We first verify the passage to the limit as $\delta_0 \rightarrow 0$. Note that there exists $p \in N$ such that, for all $a, b, c \in \mathbb{R}$,

$$|F^\beta(a, b) - F^\beta(a, c)| \leq K|b - c|(1 + |b|^p + |c|^p).$$

Therefore, upon denoting

$$\begin{aligned} \mathcal{B}_1 := & \left| E \int_{\Pi_T} \int_{\Pi_T} F^\beta(v(s, y), u(t, x)) \nabla_y \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dy ds dx dt \right. \\ & \left. - E \int_{\mathbb{R}^d} \int_{\Pi_T} F^\beta(v(s, y), u(s, x)) \nabla_y \psi(s, y) \varrho_\delta(x - y) dy ds dx \right|, \end{aligned}$$

we have

$$\begin{aligned} \mathcal{B}_1 &\leq \left| E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{\Pi_T} F^\beta(v(s, y), u(t, x)) \nabla_y \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dx dt dy ds \right. \\ &\quad \left. - E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{t=0}^T \int_{\mathbb{R}^d} F^\beta(v(s, y), u(s, x)) \nabla_y \psi(s, y) \varrho_\delta(x - y) \rho_{\delta_0}(t - s) dx dt dy ds \right| \\ &\quad + \mathcal{O}(\delta_0) \\ &\leq K \|\nabla_y \psi(s, y)\|_\infty E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{t=0}^T |u(s, x) - u(t, x)| (1 + |u(s, x)|^p + |u(t, x)|^p) \\ &\quad \times \rho_{\delta_0}(t - s) dt dx ds + \mathcal{O}(\delta_0) \\ &\quad \text{(by Cauchy–Schwartz inequality)} \\ &\leq C \|\nabla_y \psi(s, y)\|_\infty \left[E \int_{s=\delta_0}^T \int_{\mathbb{R}^d} \int_{t=0}^T |u(s, x) - u(t, x)|^2 \rho_{\delta_0}(t - s) dt dx ds \right]^{\frac{1}{2}} + \mathcal{O}(\delta_0) \\ &\leq C \|\nabla_y \psi(s, y)\|_\infty \left[E \int_{r=0}^1 \int_{\mathbb{R}^d} \int_{t=0}^T |u(t + \delta_0 r, x) - u(t, x)|^2 \rho(-r) dt dx dr \right]^{\frac{1}{2}} + \mathcal{O}(\delta_0). \end{aligned}$$

Note that, $\lim_{\delta_0 \downarrow 0} \int_0^T \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)|^2 dx dt \rightarrow 0$ almost surely for all $r \in [0, 1]$. Therefore, by bounded convergence theorem, $\lim_{\delta_0 \downarrow 0} E[\int_{r=0}^1 \int_0^T \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)|^2 \rho(-r) dx dt dr] = 0$, and therefore the first step follows.

Step 2: In this step we establish the second part of the lemma. Note that $F'_k(s)$ has at most polynomial growth in $s \in \mathbb{R}$. It follows from direct computation that there exists $p \in \mathbb{N}$ such that for all $u, v \in \mathbb{R}$ and $\beta = \beta_\varepsilon$,

$$|F_k^{\beta_\varepsilon}(v, u) - \text{sign}(u - v)(F_k(u) - F_k(v))| \leq \varepsilon C_p (1 + |u|^p + |v|^p). \tag{3.7}$$

Therefore

$$\begin{aligned} & \left| -E \left[\int_{\mathbb{R}^d} \int_{\Pi_T} F_k^{\beta_\varepsilon}(v(s, y), u(s, x)) \nabla_y \psi(s, y) \varrho_\delta(x - y) dy ds dx \right. \right. \\ & \quad \left. \left. + \int_{\mathbb{R}^d} \int_{\Pi_T} \sum_{k=1}^d \text{sign}(u(s, x) - v(s, y)) (F_k(u(s, x)) \right. \right. \\ & \quad \left. \left. - F_k(v(s, y))) \partial_{y_k} \psi(s, y) \varrho_\delta(x - y) dy ds dx \right] \right| \\ & \leq E \left[\int_{\mathbb{R}^d} \int_{\Pi_T} \sum_{k=1}^d |F_k^{\beta_\varepsilon}(v(s, y), u(s, x)) - \text{sign}(u(s, x) - v(s, y)) (F_k(u(s, x)) \right. \\ & \quad \left. - F_k(v(s, y)))| |\partial_{y_k} \psi(s, y)| \varrho_\delta(x - y) dy ds dx \right] \\ & \leq \text{Const}(\psi) \varepsilon \left[1 + \sup_{0 \leq s \leq T} E \|v(s)\|_p^p + \sup_{0 \leq s \leq T} E \|u(s)\|_p^p \right] \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0. \tag{3.8} \end{aligned}$$

Since ψ is smooth test function and F_k 's are smooth and have polynomially growing derivatives, it is easy to verify that $F(u, v) = \text{sign}(u - v)(F(u) - F(v))$ is locally Lipschitz and

$$|F(u, v) - F(\tilde{u}, v)| \leq C |u - \tilde{u}| (1 + |u|^p + |\tilde{u}|^p).$$

Therefore, we can employ dominated convergence theorem and conclude

$$\left| E \left[\int_{\Pi_T} \int_{\mathbb{R}^d} \sum_{k=1}^d \text{sign}(u(s, x) - v(s, y)) (F_k(u(s, x)) \right. \right. \\ \left. \left. - F_k(v(s, y))) \partial_{y_k} \psi(s, y) \varrho_\delta(x - y) dx dy ds \right] \right|$$

$$\begin{aligned}
 & - E \left[\int_{\Pi_T} \sum_{k=1}^d \text{sign}(u(s, y) - v(s, y)) (F_k(u(s, y)) - F_k(v(s, y))) \partial_{y_k} \psi(s, y) dy ds \right] \Bigg| \\
 & = \mathcal{O}(\delta).
 \end{aligned}$$

Therefore

$$\begin{aligned}
 & \left| E \int_{\Pi_T} \int_{\mathbb{R}^d} F^{\beta_\varepsilon}(v(s, y), u(s, x)) \nabla_y \psi(s, y) \varrho_\delta(x - y) dx dy ds \right. \\
 & \quad \left. - E \left[\int_{\Pi_T} \sum_{k=1}^d \text{sign}(u(s, y) - v(s, y)) (F_k(u(s, y)) - F_k(v(s, y))) \partial_{y_k} \psi(s, y) dy ds \right] \right| \\
 & \leq \text{Const}(\psi) \varepsilon + \mathcal{O}(\delta) \rightarrow 0 \quad \text{as } (\varepsilon, \delta) \rightarrow (0, 0). \quad \square
 \end{aligned}$$

Lemma 3.4. *It holds that*

$$\lim_{\varepsilon \downarrow 0, \frac{\varepsilon}{\delta} \downarrow 0, \delta \downarrow 0} \lim_{\delta_0 \downarrow 0} (I_4 + I_5) = 0. \tag{3.9}$$

Proof. We can use the same reasoning as before and pass to the limit $\delta_0 \downarrow 0$ and conclude

$$\begin{aligned}
 & \lim_{\delta_0 \rightarrow 0} (I_4 + I_5) \\
 & = E \left[\int_{\mathbb{R}^d} \int_{\Pi_T} \left\{ F^\beta(u(s, x), v(s, y)) \nabla_x \varrho_\delta(x - y) + F^\beta(v(s, y), u(s, x)) \right. \right. \\
 & \quad \left. \left. \times \nabla_y \varrho_\delta(x - y) \right\} \psi(s, y) dy ds dx \right] \\
 & = E \left[\int_{\mathbb{R}^d} \int_{\Pi_T} \left\{ -F^\beta(u(s, x), v(s, y)) + F^\beta(v(s, y), u(s, x)) \right\} \right. \\
 & \quad \left. \times \nabla_y \varrho_\delta(x - y) \psi(s, y) dy ds dx \right].
 \end{aligned}$$

Note that, there exists $p \in \mathbb{N}$, such that for all $a, b \in \mathbb{R}$

$$\begin{aligned}
 & |F_k^{\beta_\varepsilon}(a, b) - F_k^{\beta_\varepsilon}(b, a)| \\
 & \leq |F_k^{\beta_\varepsilon}(a, b) - \text{sign}(a - b)(F_k(a) - F_k(b))| + |F_k^{\beta_\varepsilon}(b, a) - \text{sign}(b - a)(F_k(b) - F_k(a))| \\
 & \leq C\varepsilon(1 + |a|^p + |b|^p).
 \end{aligned}$$

Therefore,

$$\begin{aligned} & \left| E \left[\int_{\mathbb{R}^d} \int_{\Pi_T} \{ F^\beta(u(s, x), v(s, y)) - F^\beta(v(s, y), u(s, x)) \} \nabla_y \varrho_\delta(x - y) \psi(s, y) dy ds dx \right] \right| \\ & \leq \varepsilon CE \left[\int_{\mathbb{R}^d} \int_{\Pi_T} (1 + |u(s, x)|^p + |v(s, y)|^p) |\nabla_y \varrho_\delta(x - y)| \psi(s, y) dy ds dx \right] \\ & \leq \frac{\varepsilon}{\delta} C \rightarrow 0 \quad \text{when } \left(\varepsilon, \frac{\varepsilon}{\delta}, \delta \right) \rightarrow (0, 0, 0). \end{aligned}$$

Hence the lemma follows. \square

Lemma 3.5. *The following hold:*

$$\lim_{\delta_0 \rightarrow 0} I_6 = \frac{1}{2} E \int_{\Pi_T} \int_{\mathbb{R}^d} \sigma^2(x, u(s, x)) \beta''(u(s, x) - v(s, y)) \psi(s, y) \varrho_\delta(x - y) dx dy ds \tag{3.10}$$

and

$$\lim_{\delta_0 \rightarrow 0} I_7 = \frac{1}{2} E \int_{\Pi_T} \int_{\mathbb{R}^d} \sigma^2(y, v(s, y)) \beta''(v(s, y) - u(s, x)) \psi(s, y) \varrho_\delta(x - y) dx dy ds. \tag{3.11}$$

Proof. We will rigorously establish (3.10) and (3.11). Note that

$$I_6 = \frac{1}{2} E \int_{\Pi_T \times \Pi_T} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(s, y)) \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dx dy ds dt.$$

Therefore,

$$\begin{aligned} & \left| I_6 - \frac{1}{2} E \int_{\Pi_T} \int_{\mathbb{R}^d} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(t, y)) \psi(t, y) \varrho_\delta(x - y) dx dy dt \right| \\ & = \left| I_6 - \frac{1}{2} E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} \sigma^2(x, u(t, x)) \beta''(u(t, x) - v(t, y)) \psi(t, y) \right. \\ & \quad \left. \times \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dx dy dt ds \right| + \mathcal{O}(\delta_0) \\ & \leq E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} \sigma^2(x, u(t, x)) |\beta''(u(t, x) - v(t, y)) - \beta''(u(t, x) - v(s, y))| \end{aligned}$$

$$\begin{aligned}
 & \times \psi(s, y)\rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds \\
 & + E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} \sigma^2(x, u(t, x))\beta''(u(t, x) - v(t, y))|\psi(t, y) - \psi(s, y)| \\
 & \times \rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds + \mathcal{O}(\delta_0) \\
 \leq & \|\beta'''\|_{\infty} E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} \sigma^2(x, u(t, x))|v(s, y) - v(t, y)|\psi(s, y) \\
 & \times \rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds + \mathcal{O}(\delta_0) \\
 \leq & \text{Const}(\beta, \eta) E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} g^2(x)(1 + |u(t, x)|^2)|v(s, y) - v(t, y)| \\
 & \times \psi(s, y)\rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds + \mathcal{O}(\delta_0) \\
 & \text{(by Cauchy–Schwartz)} \\
 \leq & \text{Const}(\beta, \eta) \\
 & \times \sqrt{E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} g^4(x)(1 + |u(t, x)|^4)\psi(s, y)\rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds} \\
 & \times \sqrt{E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d \times \mathbb{R}^d} |v(s, y) - v(t, y)|^2\psi(s, y)\rho_{\delta_0}(t - s)\varrho_{\delta}(x - y) \, dx \, dy \, dt \, ds + \mathcal{O}(\delta_0)} \\
 \leq & \text{Const}(\beta, \eta, \psi) \sqrt{E \int_{s=\delta_0}^T \int_{t=0}^T \int_{\mathbb{R}^d} |v(s, y) - v(t, y)|^2\rho_{\delta_0}(t - s) \, dy \, dt \, ds + \mathcal{O}(\delta_0)} \\
 \leq & \text{Const}(\beta, \eta, \psi) \sqrt{E \int_{r=0}^1 \int_{t=0}^T \int_{\mathbb{R}^d} |v(t, x) - v(t + r\delta_0, x)|^2\rho(-r) \, dx \, dt \, dr + \mathcal{O}(\delta_0)}.
 \end{aligned}$$

Once again we use the fact that $\lim_{\delta_0 \downarrow 0} \int_0^T \int_{\mathbb{R}^d} |u(t + \delta_0 r, x) - u(t, x)|^2 \, dx \, dt \rightarrow 0$. Therefore, by dominated convergence theorem, $E \int_{r=0}^1 \int_{t=0}^T \int_{\mathbb{R}^d} |v(t, y) - v(t + r\delta_0, y)|^2 \cdot \rho(-r) \, dy \, dt \, dr \rightarrow 0$ as $\delta_0 \rightarrow 0$. The proof of (3.11) is similar. \square

Lemma 3.6. *It holds that*

$$\begin{aligned}
 \lim_{\delta_0 \rightarrow 0} I_8 = & -E \int_{\Pi_T} \int_{\mathbb{R}^d} \sigma(x, u(t, x)) \\
 & \times \sigma(y, v(t, y))\beta''(u(t, x) - v(t, y))\psi(t, y)\varrho_{\delta}(x - y) \, dy \, dx \, dt. \tag{3.12}
 \end{aligned}$$

Proof. Recall that

$$I_8 = -E \int_{\Pi_T} \int_{\Pi_T} \sigma(x, u(t, x)) \sigma(y, v(t, y)) \times \beta''(u(t, x) - v(t, y)) \psi(s, y) \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dy dx dt ds.$$

Therefore, as before,

$$\begin{aligned} & \left| I_8 + E \int_{\Pi_T} \int_{\mathbb{R}^d} \sigma(x, u(t, x)) \sigma(y, v(t, y)) \beta''(u(t, x) - v(t, y)) \psi(t, y) \varrho_\delta(x - y) dy dx dt \right| \\ & \leq E \int_{s=\delta_0}^T \int_{\Pi_T} \int_{\mathbb{R}^d} |\sigma(x, u(t, x)) \sigma(y, v(t, y))| |\beta''(u(t, x) - v(t, y))| |\psi(s, y) - \psi(t, y)| \\ & \quad \times \rho_{\delta_0}(t - s) \varrho_\delta(x - y) dy dx dt ds + \mathcal{O}(\delta_0) \\ & \leq \delta_0 \|\partial_t \psi\|_\infty \|\beta''\|_\infty E \int_{\Pi_T} \int_{\mathbb{R}^d} |\sigma(x, u(t, x)) \sigma(y, v(t, y))| \varrho_\delta(x - y) dy dx dt + \mathcal{O}(\delta_0) \\ & \leq \delta_0 \|\partial_t \psi\|_\infty \|\beta''\|_\infty C \left(1 + \sup_{0 \leq t \leq T} E \|u(t, \cdot)\|_2^2 + \sup_{0 \leq t \leq T} E \|v(t, \cdot)\|_2^2 \right) + \mathcal{O}(\delta_0). \end{aligned}$$

Hence the lemma follows by simply letting $\delta_0 \downarrow 0$ in the last line. \square

Lemma 3.7. Assume that $\varepsilon \rightarrow 0^+$, $\delta \rightarrow 0^+$ and $\varepsilon^{-1} \delta^2 \rightarrow 0^+$, then

$$\limsup_{\varepsilon \rightarrow 0^+, \delta \rightarrow 0^+, \varepsilon^{-1} \delta^2 \rightarrow 0^+} \lim_{\delta_0 \rightarrow 0} (I_6 + I_7 + I_8) = 0$$

Proof. Since β'' is even function, we have from [Lemma 3.5](#) and [Lemma 3.6](#) that

$$\begin{aligned} & \lim_{\delta_0 \rightarrow 0} (I_6 + I_7 + I_8) \\ & = \frac{1}{2} E \left[\int_{\Pi_T} \int_{\mathbb{R}^d} (\sigma(x, u(s, x)) - \sigma(y, v(s, y)))^2 \beta''(u(s, x) - v(s, y)) \psi(s, y) \varrho_\delta(x - y) dx dy ds \right] \end{aligned}$$

Now, by our assumption on σ , we have

$$\begin{aligned} & (\sigma(x, u(s, x)) - \sigma(y, v(s, y)))^2 \beta''(u(s, x) - v(s, y)) \\ & \leq C(|x - y|^2 + |u(s, x) - v(s, y)|^2) \beta''(u(s, x) - v(s, y)) \\ & \leq C \left(\varepsilon + \frac{|x - y|^2}{\varepsilon} \right) \end{aligned}$$

Therefore,

$$E \left[\int_{(0,T]} \int_{x,y} (\sigma(x, u(s, x)) - \sigma(y, v(s, y)))^2 \beta''(u(s, x) - v(s, y)) \psi(s, y) \varrho_\delta(x - y) dx dy ds \right] \leq C_1(\varepsilon + \varepsilon^{-1}\delta^2)T,$$

and letting $\varepsilon \rightarrow 0^+$, $\delta \rightarrow 0^+$ and $\varepsilon^{-1}\delta^2 \rightarrow 0^+$ gets us to the desired conclusion. \square

Theorem 3.8. *Assume (A.1)–(A.3). Suppose u is a stochastic entropy solution of (1.1) and v is a stochastic strong entropy solution of the same equation. Then*

$$E[\| (u(t) - v(t)) \|_1] \leq E[\| (u(0) - v(0)) \|_1]$$

for almost every $t > 0$.

Proof. First we pass to the limit $\delta_0 \downarrow 0$ in (3.4) and then let $\delta = \varepsilon^{\frac{2}{3}}$ and finally let $\varepsilon \downarrow 0$. We use Lemmas 3.1–3.7 along with the preceding inequality (3.4) and obtain

$$E \left[\int_{\mathbb{R}^d} |u_0(x) - v_0(x)| \psi(0, x) dx \right] + E \left[\int_{\Pi_T} |v(t, x) - u(t, x)| \partial_t \psi(t, x) dt dx \right] + E \left[\int_{\Pi_T} F(u(t, x), v(t, x)) \cdot \nabla_x \psi(t, x) dt dx \right] \geq 0 \tag{3.13}$$

For each $n \in \mathbb{N}$, define

$$\phi_n(x) = \begin{cases} 1, & \text{if } |x| \leq n \\ 2(1 - \frac{|x|}{2n}), & \text{if } n < |x| \leq 2n \\ 0, & \text{if } |x| > 2n. \end{cases}$$

For each $h > 0$ and fixed $t \geq 0$, define

$$\psi_h(s) = \begin{cases} 1, & \text{if } s \leq t \\ 1 - \frac{s-t}{h}, & \text{if } t \leq s \leq t+h \\ 0, & \text{if } s > t+h. \end{cases}$$

By standard approximation, truncation and mollification argument, (3.13) holds with $\psi(s, x) = \phi_n(x)\psi_h(s)$. Define

$$A(s) = E \left[\int_{\mathbb{R}^d} |u(s, x) - v(s, x)| dx \right],$$

then $A \in L^1_{\text{loc}}([0, \infty))$. It is trivial to check that any right Lebesgue point of $A(t)$ is also a right Lebesgue point of

$$A_n(s) = E \left[\int_{\mathbb{R}^d} \phi_n(x) |u(s, x) - v(s, x)| dx \right]$$

for all n . Let t be a right Lebesgue point of A . We choose this t in the definition of $\psi_h(s)$. Thus, from (3.13) we have

$$\begin{aligned} & \frac{1}{h} \int_t^{t+h} E \left[\int_{\mathbb{R}^d} |v(s, x) - u(s, x)| \phi_n(x) dx \right] ds \\ & \leq E \left[\int_{H_T} F(u(s, x), v(s, x)) \cdot \nabla_x \phi_n(x) \psi_h(s) ds dx \right] \\ & \quad + E \left[\int_{\mathbb{R}^d} |u_0(x) - v_0(x)| \phi_n(x) dx \right]. \end{aligned}$$

Taking limit as $h \rightarrow 0$, we obtain

$$\begin{aligned} & E \left[\int_{\mathbb{R}^d} |v(t, x) - u(t, x)| \phi_n(x) dx \right] \\ & \leq E \left[\int_{\mathbb{R}^d} \int_0^t F(u(s, x), v(s, x)) \cdot \nabla_x \phi_n(x) ds dx \right] \\ & \quad + E \left[\int_{\mathbb{R}^d} |u_0(x) - v_0(x)| \phi_n(x) dx \right] \\ & \leq C(T) \frac{1}{n} \left[1 + \sup_{0 \leq s \leq T} E \|u(s)\|_p^p + \sup_{0 \leq s \leq T} E \|v(s)\|_p^p \right] \\ & \quad + E \left[\int_{\mathbb{R}^d} |u_0(x) - v_0(x)| \phi_n(x) dx \right] \tag{3.14} \end{aligned}$$

Letting $n \rightarrow \infty$, we have from (3.14)

$$E [\| (u(t) - v(t)) \|_1] \leq E [\| (u(0) - v(0)) \|_1]. \quad \square$$

Theorem 3.9 (*Comparison principle*). *Assume (A.1)–(A.3). Suppose u is a stochastic entropy solution of (1.1) and v is a stochastic strong entropy solution. Then for almost every $t > 0$,*

$$E[\|(u(t) - v(t))_+\|_1] \leq E[\|(u(0) - v(0))_+\|_1].$$

Consequently, if $v(0, x) \leq u(0, x)$ a.e. in x holds almost surely, and that $E[\|(u(0, \cdot) - v(0, \cdot))_+\|_1] < \infty$, then almost surely $v(t, x) \leq u(t, x)$ a.e. in x , and almost every $t > 0$.

Proof. The proof is exactly the same as that of [Theorem 3.8](#), if we choose $(\beta_\epsilon(r))_\epsilon$ to be a smooth convex approximation of $r_+ = \max(0, r)$. \square

Proof of Theorem 2.2. It is given that u is a stochastic entropy solution of [\(1.1\)](#) and v is a stochastic strong entropy solution and $\bigcap_{p=1,2,\dots} L^p(\mathbb{R}^d)$ -valued random variable u_0 satisfies

$$E[\|u_0\|_p^p + \|u_0\|_2^p] < \infty, \quad p = 1, 2, \dots$$

Therefore by [Theorem 3.8](#), as $u(0) = v(0)$ almost surely, we have $u(t) = v(t)$ for almost every t . Hence the uniqueness is proved. \square

4. Vanishing viscosity and existence of entropy solutions

In this section, we detail the mechanism of proving existence of entropic solution. Just as the deterministic problem, here also we apply vanishing viscosity method. We must mention that a number of recent studies, including Feng and Nualart [\[8\]](#), use this approach to establish existence for conservation laws driven by noise. However, this method requires rigorous wellposedness results along with a few crucial a priori estimates for the viscous problem which allows one to apply stochastic compensated compactness and get the existence. It is to be mentioned also that we need to exercise utmost caution while extracting an inviscid limit out of the vanishing viscosity approximations. The apparent inconsistencies, which are the motivations for this paper, in [\[8\]](#) are largely due to the inadequacies in handling the limiting procedure.

It must be admitted here that, in [\[8\]](#), the authors offer a rigorous and flawless study of the wellposedness question of viscous problem along with necessary a priori estimates. In the first part of this section we state the relevant results without proof.

4.1. Viscous approximation

Let $J \in C_c^\infty(\mathbb{R})$ be the one dimensional mollifier and $\varphi \in C_c^\infty(\mathbb{R})$ be a cut-off function satisfying

$$\varphi(r) = \begin{cases} 0 & \text{for } |r| \geq 2 \\ 1 & \text{for } |r| \leq 1. \end{cases}$$

For $\epsilon > 0$, define the approximates $F_\epsilon(r)$ and $\sigma_\epsilon(x, u)$ as

$$F_\epsilon(r) = \varphi(\epsilon|r|^2)F(r) * J_\epsilon(r)$$

$$\sigma_\epsilon(x, u) = \int_y \int_v \left(\prod_{k=1}^d J_\epsilon(x_k - y_k) J_\epsilon(u - v) \right) \varphi(\epsilon(|y|^2 + |v|^2)) \sigma(y, v) \, dv \, dy,$$

and introduce the viscous perturbation of (1.1):

$$\begin{aligned} du_\epsilon(t, x) + \operatorname{div}_x F_\epsilon(u_\epsilon(t, x)) \, dt \\ = \sigma_\epsilon(x, u_\epsilon(t, x)) dW(t) + \epsilon \Delta_{xx} u_\epsilon(t, x) \, dt \quad t > 0, \, x \in \mathbb{R}^d, \end{aligned} \tag{4.1}$$

with the regularized initial condition

$$u_\epsilon(0, x) = \int_y \left(\prod_{k=1}^d J_\epsilon(x_k - y_k) u_0(y) \varphi(\epsilon|y|^2) \right) dy. \tag{4.2}$$

It follows from direct computation that

$$\begin{aligned} |F_\epsilon(r) - F(r)| &\leq C\epsilon(1 + |r|^{2p_0}) \quad \text{for some } p_0 \in \mathbb{N} \\ |\sigma_\epsilon(x, u) - \sigma(x, u)| &\leq C\epsilon g(x)(1 + |u|). \end{aligned} \tag{4.3}$$

As expected, the perturbation (4.1) is uniquely solvable and has smooth solution. We have the following proposition, a proof of which could be found in [8].

Proposition 4.1. *Let (A.1)–(A.3) hold and $\epsilon > 0$ be a positive number. Then there is a unique $C^2(\mathbb{R}^d)$ -valued predictable process $u_\epsilon(t, \cdot)$ which solves the initial value problem (4.1)–(4.2). Moreover,*

1) *For positive integers $p = 2, 3, 4, \dots$*

$$\sup_{\epsilon > 0} \sup_{0 \leq t \leq T} E[\|u_\epsilon(t, \cdot)\|_p^p] < +\infty \tag{4.4}$$

2) *For $\phi \in C^2(\mathbb{R})$ with ϕ, ϕ', ϕ'' having at most polynomial growth*

$$\begin{aligned} \sup_{\epsilon > 0} E \left[\left\| \int_0^T \int_{\mathbb{R}^d} \phi''(u_\epsilon(t, x)) |\nabla_x u_\epsilon(t, x)|^2 \, dx \, dt \right\|^p \right] < \infty, \\ p = 1, 2, \dots, T > 0. \end{aligned} \tag{4.5}$$

Our solution method relies upon being able to extract a convergent subsequence out of the family $\{u_\epsilon\}_{\epsilon > 0}$ in an appropriate sense. However, it is needless to mention that the above moment estimates (4.4) and (4.5) are not enough to ensure compactness of

the family $\{u_\epsilon(t, x)\}$ in the classical L^p sense. Moreover, our main emphasis is to avoid “strong in time” framework of Feng and Nualart at any cost and we do not find it appropriate to treat the family $\{u_\epsilon\}_{\epsilon>0}$ as measure valued processes and look for convergence in the space of measure valued processes. This prompts us to follow [2] and consider the family $\{u_\epsilon\}_{\epsilon>0}$ as a family of Young measures parametrized by $(\omega; t, x)$ and look for tightness to enable us to extract a convergence subsequence. We need to recall some of the basic features and facts about the Young measure, which is done below.

4.2. Some basic facts about Young measures

Roughly speaking a Young measure is a parametrized family of probability measures where the parameters are drawn from a σ -finite measure space. Its definition requires a σ -finite measure space (Θ, Σ, μ) and we denote by $\mathcal{P}(\mathbb{R})$ the space of probability measures on \mathbb{R} .

Definition 4.1 (*Young measure*). A Young measure from Θ into \mathbb{R} is a map $\nu \mapsto \mathcal{P}(\mathbb{R})$ such that $\nu(\cdot) : \theta \mapsto \nu(\theta)(B)$ is Σ -measurable for every Borel subset B of \mathbb{R} . The set of all Young measures from Θ into \mathbb{R} is denoted by $\mathcal{R}(\Theta, \Sigma, \mu)$ or simply by \mathcal{R} .

Remark. Trivially, if $u(\theta)$ is a real valued measurable function on (Θ, Σ, μ) then $\nu(\theta) = \delta(\xi - u(\theta))$ defines a Young measure on Θ . In other words, with an appropriate choice of (Θ, Σ, μ) , the family $\{u_\epsilon(t, x)\}_{\epsilon>0}$ can be thought of as a family of Young measures and we are interested in finding a subsequence out of this family that ‘converges’ to a Young measure as ϵ goes to 0. This obviously calls for clarification of the term *convergence* in this context. It turns out that the notion of “narrow convergence” of Young measures is the most suitable to our context.

Definition 4.2 (*Narrow convergence*). A sequence of Young measures ν_n in \mathcal{R} is said to converge *narrowly* to ν iff for every $A \in \Sigma$ and $h \in C_b(\mathbb{R})$

$$\lim_{n \rightarrow \infty} \int_A \left[\int_{\mathbb{R}} h(\xi) \nu_n(\theta)(d\xi) \right] \mu(d\theta) = \int_A \left[\int_{\mathbb{R}} h(\xi) \nu(\theta)(d\xi) \right] \mu(d\theta).$$

Next, we specify the tightness criterion for Young measures.

Definition 4.3 (*Tightness*). A family of Young measures $\{\nu_n\}_n$ in \mathcal{R} is called tight if there exists an inf-compact integrand h on $\Theta \times \mathbb{R}$ such that

$$\sup_n \int_{\Theta} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu_n(\theta)(d\xi) \right] \mu(d\theta) < \infty.$$

Remark. Without getting into much details on the entire class of inf-compact functions, it is enough for us to know that $h(\theta, \xi) = \xi^2$ is one such example. With this choice of h

and an appropriate choice of (Θ, Σ, μ) , by (4.4) the family $\{u_\epsilon(t, x)\}_{\epsilon>0}$ is tight when viewed as family of Young measures.

The tightness condition enables us to extract a subsequence from a tight family and we have the following version of Prohorov’s theorem to this end, a detailed proof which could be found in [1].

Theorem 4.2. (1) [Prohorov’s theorem] Let (Θ, Σ, μ) be a finite measure space and $\{\nu_n\}_n$ be a tight family of Young measures in \mathcal{R} . Then there exists a subsequence $\{\nu_{n'}\}$ of $\{\nu_n\}_n$ and $\nu \in \mathcal{R}$ such that $\{\nu_{n'}\}$ converges narrowly to ν .

(2) Moreover, with $\nu_n = \delta_{f_n(\theta)}(\xi)$ and given a Caratheodory function $h(\theta, \xi)$ on $\Theta \times \mathbb{R}$, if $h(\theta, f_{n'}(\theta))$ is uniformly integrable then

$$\lim_{n' \rightarrow \infty} \int_{\Theta} h(\theta, f_{n'}(\theta)) \mu(d\theta) = \int_{\Theta} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu(\theta)(d\xi) \right] \mu(d\theta).$$

4.3. The inviscid Young measure limit of $\{u_\epsilon(t, x)\}_{\epsilon>0}$

Let \mathcal{P}_T be the predictable σ -field on $\Omega \times (0, T)$ with respect to the filtration $\{\mathcal{F}_t\}_{0 \leq t \leq T}$. Furthermore, we set

$$\Theta = \Omega \times (0, T) \times \mathbb{R}^d, \quad \Sigma = \mathcal{P}_T \times \mathcal{L}(\mathbb{R}^d) \quad \text{and} \quad \mu = P \otimes \lambda_t \otimes \lambda_x,$$

where λ_t and λ_x are respectively the Lebesgue measures on $(0, T)$ and \mathbb{R}^d , and $\mathcal{L}(\mathbb{R}^d)$ be the Lebesgue σ -algebra on \mathbb{R}^d . Note that the family $\{u_\epsilon(t, x)\}_{\epsilon>0}$ could be viewed as a tight family in $\mathcal{R}(\Theta, \Sigma, \mu)$, but (Θ, Σ, μ) is not a finite measure space. Hence Theorem 4.2 cannot be readily applied to $\{u_\epsilon(t, x)\}_{\epsilon>0}$. We follow [2] and get this problem with the following considerations.

For any natural number M , let

$$\Theta_M = \Omega \times (0, T) \times B_M, \quad \Sigma_M = \mathcal{P}_T \times \mathcal{L}(B_M) \quad \text{and} \quad \mu_M = \mu|_{\Theta_M},$$

where B_M is the ball of radius M around zero in \mathbb{R}^d and $\mathcal{L}(B_M)$ is the Lebesgue σ -algebra on B_M . It is easily seen that $(\Theta_M, \Sigma_M, \mu_M)$ is a finite measure space and $\{u_\epsilon(\omega; t, x)\}_{\epsilon>0}$ (when restricted to Θ_M) is a tight family of Young measures in $\mathcal{R}(\Theta_M, \Sigma_M, \mu_M)$. Therefore by Theorem 4.2, there exists subsequence $\epsilon_n \rightarrow 0$ and $\nu^M \in \mathcal{R}(\Theta_M, \Sigma_M, \mu_M)$ such that $\{u_{\epsilon_n}(\omega; t, x)\}$ converges narrowly to ν^M .

In addition, for $\bar{M} > M$, the sequence $\{u_{\epsilon_n}(\omega; t, x)\}$ is tight in $\mathcal{R}(\Theta_{\bar{M}}, \Sigma_{\bar{M}}, \mu_{\bar{M}})$, and hence admits a further subsequence, say $\{u_{\epsilon_{n'}}(\omega; t, x)\}$, and $\nu^{\bar{M}} \in \mathcal{R}(\Theta_{\bar{M}}, \Sigma_{\bar{M}}, \mu_{\bar{M}})$ such that $\{u_{\epsilon_{n'}}(\omega; t, x)\}$ converges narrowly to $\nu^{\bar{M}}$. We now invoke diagonalization and conclude that there exists a subsequence $\{u_{\epsilon_{n'}}(\omega; t, x)\}$ with $\epsilon_n \rightarrow 0$ and Young measures $\nu^M \in \mathcal{R}(\Theta_M, \Sigma_M, \mu_M)$, $M = 1, 2, 3, \dots$ such that $\{u_{\epsilon_n}(\omega; t, x)\}$ converges narrowly to ν^M

in $\mathcal{R}(\Theta_M, \Sigma_M, \mu_M)$ for every $M = 1, 2, \dots$. In view of [Theorem 4.2](#), it is easily concluded that

$$\text{if } \bar{M} > M \text{ then } \nu^M = \nu^{\bar{M}} \quad \mu\text{-a.e. on } (\Theta_M, \Sigma_M, \mu).$$

Now define

$$\nu_{(\omega;t,x)} = \nu_{(\omega;t,x)}^M \quad \text{if } (\omega; t, x) \in \Theta_M. \tag{4.6}$$

Clearly, ν is well defined as a Young measure in $\mathcal{R}(\Theta, \Sigma, \mu)$. This reasoning could now be summarized into the following lemma.

Lemma 4.3. *Let $\{u_\varepsilon(t, x)\}_{\varepsilon>0}$ be a sequence of $L^p(\mathbb{R}^d)$ -valued predictable processes such that (4.4) holds. Then there exist a subsequence $\{\varepsilon_n\}$ with $\varepsilon_n \rightarrow 0$ and a Young measure $\nu \in \mathcal{R}(\Theta, \Sigma, \mu)$ such that the following holds:*

If $h(\theta, \xi)$ is a Caratheodory function on $\Theta \times \mathbb{R}$ such that $\text{supp}(h) \subset \Theta_M \times \mathbb{R}$ for some $M \in \mathbb{N}$ and $\{h(\theta, u_{\varepsilon_n}(\theta))\}_n$ (where $\theta \equiv (\omega; t, x)$) is uniformly integrable, then

$$\lim_{\varepsilon_n \rightarrow 0} \int_{\Theta} h(\theta, u_{\varepsilon_n}(\theta)) \mu(d\theta) = \int_{\Theta} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu(\theta)(d\xi) \right] \mu(d\theta).$$

Proof. The extraction of subsequence is done as described above and ν is defined in (4.6). Note that if $M \in \mathbb{N}$ such that $\text{supp}(h) \subset \Theta_M \times \mathbb{R}$, then

$$\begin{aligned} \int_{\Theta} h(\theta, u_{\varepsilon_n}(\theta)) \mu(d\theta) &= \int_{\Theta_M} h(\theta, u_{\varepsilon_n}(\theta)) \mu_M(d\theta) \quad \text{and} \\ \int_{\Theta} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu(\theta)(d\xi) \right] \mu(d\theta) &= \int_{\Theta_M} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu^M(\theta)(d\xi) \right] \mu_M(d\theta), \end{aligned}$$

and the convergence simply follows from [Theorem 4.2](#). \square

To this end, we intend to show that the Young measure $\nu(\theta)(du)$ has a point mass, i.e. there is a (Θ, Σ, μ) -measurable function \bar{u} such that for any Caratheodory function $h(\theta, \xi)$ on $\Theta \times \mathbb{R}$

$$\int_{\Theta} \left[\int_{\mathbb{R}} h(\theta, \xi) \nu(\theta)(d\xi) \right] \mu(d\theta) = \int_{\Theta} h(\theta, \bar{u}(\theta)) \mu(d\theta)$$

whenever the integrals make sense. In other words, upon writing $\theta \equiv (\omega; t, x)$ we want to find out a $\mathcal{P}_T \times \mathcal{L}(\mathbb{R}^d)$ measurable function $\bar{u}(\omega; t, x)$ such that

$$E \left[\int_{\Pi_T} \left[\int_{\mathbb{R}} h(\omega; t, x, \xi) \nu(\omega; t, x)(d\xi) \right] dt dx \right] = E \left[\int_{\Pi_T} h(\omega; t, x, \bar{u}(\omega; t, x)) dt dx \right]. \tag{4.7}$$

Equivalently, all that is required to be established is that $\nu(\theta)(d\xi) = \delta_{\bar{u}(\theta)}(\xi) d\xi$ for μ -almost every $\theta \in \Theta$. This is a fairly subtle point and we use idea of stochastic compensated compactness from [8] to validate this for $d = 1$.

4.4. Stochastic compensated compactness

For a continuous and polynomially growing function $f : \mathbb{R} \rightarrow \mathbb{R}$, define

$$\bar{f}(\omega; t, x) = \int_{\xi} f(\xi) \nu(\omega; t, x)(d\xi).$$

Then $\bar{f}(\omega; t, x)$ is $\mathcal{P}_T \times \mathcal{L}(\mathbb{R}^d)$ measurable and, by (4.4), $\bar{f} \in L^p(\Theta, \Sigma, \mu)$. We further denote

$$\bar{u}(\omega; t, x) = \int_{\xi} \xi \nu(\omega; t, x)(d\xi).$$

Lemma 4.4. *It holds that*

$$\sup_{0 \leq t \leq T} E \int_{\mathbb{R}^d} |\bar{u}(\omega; t, x)|^p dx < \infty$$

for $p = 2, 3, 4, \dots$, and hence $(\omega, t) \mapsto \bar{u}(\omega; t, x)$ is a \mathcal{P}_T -measurable and $L^2(\mathbb{R}^d)$ -valued process.

Proof. Let g be a Lebesgue measurable function on $(0, T)$ and $g \in L^1((0, T))$. Then, for every $M \in \mathbb{N}$, by Lemma 4.3,

$$\begin{aligned} \int_0^T g(t) E \int_{B_M} |\bar{u}(\omega; t, x)|^p dx dt &\leq E \int_0^T \int_{B_M} \left[\int_{\xi} g(t) |\xi|^p \nu(\omega; t, x)(d\xi) \right] dx dt \\ &= \lim_{\epsilon_n \rightarrow 0} E \int_0^T \int_{B_M} g(t) \left[\int_{\xi} |\xi|^p \delta_{u_{\epsilon_n}(\omega; t, x)}(d\xi) \right] dx dt \\ &= \lim_{\epsilon_n \rightarrow 0} E \int_0^T \int_{B_M} g(t) |u_{\epsilon_n}(t, x)|^p dx dt \\ &\leq \|g\|_{L^1((0, T))} \sup_{\epsilon} \sup_{0 \leq t \leq T} E [\|u_{\epsilon}(t, \cdot)\|_p^p]. \end{aligned}$$

Note that the last line is independent of M , therefore by letting M to infinity in the first expression we have

$$\int_0^T g(t) E \int_{\mathbb{R}^d} |\bar{u}(\omega; t, x)|^p dx dt \leq \|g\|_{L^1((0,T))} \sup_{\epsilon} \sup_{0 \leq t \leq T} E [\|u_\epsilon(t, \cdot)\|_p^p]$$

for all $g \in L^1((0, T))$, which implies that $E\|\bar{u}(t, \cdot)\|_p^p \in L^\infty((0, T))$. \square

Next we state the main result of this subsection.

Lemma 4.5. *Assume that $d = 1$ and (A.1)–(A.3) hold. Then it holds that*

$$F(\bar{u}(\theta))\mu(d\theta) = \left[\int_{\xi \in \mathbb{R}} F(\xi)\nu(\theta)(d\xi) \right] \mu(d\theta). \tag{4.8}$$

In addition, if (A.4) holds, then

$$\nu(\theta)(du)\mu(d\theta) = \delta_{\bar{u}(\theta)}(du)\mu(d\theta). \tag{4.9}$$

Remark. If we expand our notation and write $\theta = (\omega; t, x)$, then (4.8) simply means that for any Σ -measurable function $h((\omega; t, x))$ on Θ , it holds that

$$\begin{aligned} & \int_{\Omega} \int_{\Pi_T} \left[\int_{\xi} h((\omega; t, x)) F(\xi)\nu(\omega; t, x)(d\xi) \right] dx dt dP(\omega) \\ &= E \int_{\Pi_T} h((\omega; t, x)) F(\bar{u}(\omega; t, x)) dx dt, \end{aligned}$$

provided the integrals make sense. Similarly, (4.9) means that for any given Caratheodory function $h((\omega; t, x), \xi)$ on $\Theta \times \mathbb{R}$, one has

$$\int_{\Omega} \int_{\Pi_T} \left[\int_{\xi} h((\omega; t, x), \xi)\nu(\omega; t, x)(d\xi) \right] dx dt dP(\omega) = E \int_{\Pi_T} h((\omega; t, x), \bar{u}(\omega; t, x)) dx dt.$$

The proof of Lemma 4.5 requires the application of a stochastic version of div–curl lemma, and [8, Theorem A.2] is such a version. Let us also mention that we find the proof of [8, Theorem A.2] to be absolutely flawless and will be using it here too. The next lemma is an important technical step to prove Lemma 4.5.

Lemma 4.6. *Let $(\Phi_i, \Psi_i), i = 1, 2$ be two choices of entropy flux pairs, where Φ_i ’s have at most polynomial growth (therefore Ψ_i will have at most polynomial growth as well). For every deterministic $\psi \in C_c^\infty(\Pi_T)$,*

$$\langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle \stackrel{D}{=} \langle \psi, \overline{\Psi_1} \cdot \overline{\Phi_2} - \overline{\Phi_1} \cdot \overline{\Psi_2} \rangle \tag{4.10}$$

Proof. Let $\psi \in C_c^\infty(\Pi_T)$ and $B \in \mathcal{F}_T$. Define

$$\begin{aligned}
 X_\varepsilon(\omega) &:= \int_{\Pi_T} \psi(t, x) (\Psi_1(u_\varepsilon(t, x)) \Phi_2(u_\varepsilon(t, x)) \\
 &\quad - \Phi_1(u_\varepsilon(t, x)) \Psi_2(u_\varepsilon(t, x))) \, dx \, dt.
 \end{aligned}
 \tag{4.11}$$

Note that, by martingale representation theorem, there exists a continuous martingale Z_t such that $Z_T = \mathbf{1}_B$. Then

$$\begin{aligned}
 &\lim_{\varepsilon_n \rightarrow 0^+} E[\mathbf{1}_B(\omega) X_{\varepsilon_n}(\omega)] \\
 &= \lim_{\varepsilon_n \rightarrow 0^+} \int_{\Pi_T} E[E[\mathbf{1}_B(\omega) | \mathcal{F}_t] \psi(t, x) (\Psi_1(u_{\varepsilon_n}(t, x)) \Phi_2(u_{\varepsilon_n}(t, x)) \\
 &\quad - \Phi_1(u_{\varepsilon_n}(t, x)) \Psi_2(u_{\varepsilon_n}(t, x)))] \, dx \, dt \\
 &= \lim_{\varepsilon_n \rightarrow 0^+} \int_{\Pi_T} E[Z_t \psi(t, x) (\Psi_1(u_{\varepsilon_n}(t, x)) \Phi_2(u_{\varepsilon_n}(t, x)) \\
 &\quad - \Phi_1(u_{\varepsilon_n}(t, x)) \Psi_2(u_{\varepsilon_n}(t, x)))] \, dx \, dt \\
 &\quad \text{(by Lemma 4.3)} \\
 &= \int_{\Pi_T} E \left[Z_t \psi(t, x) \left(\int_u (\Psi_1(u) \Phi_2(u) - \Phi_1(u) \Psi_2(u)) \nu(\omega; t, x)(du) \right) \right] \, dx \, dt \\
 &= \int_{\Omega} \int_{\Pi_T} \mathbf{1}_B(\omega) \psi(t, x) \left(\int_u (\Psi_1(u) \Phi_2(u) - \Phi_1(u) \Psi_2(u)) \nu(\omega; t, x)(du) \right) \, dx \, dt \, dP(\omega) \\
 &= \int_{\Omega} \int_{\Pi_T} \mathbf{1}_B(\omega) \psi(t, x) (\overline{\Psi_1 \Phi_2}(\theta) - \overline{\Phi_1 \Psi_2}(\theta)) \, dt \, dx \, dP(\omega) \\
 &= \int_{\Omega} \mathbf{1}_B(\omega) \langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle(\omega) \, dP(\omega) \\
 &\equiv \int_{\Omega} \mathbf{1}_B(\omega) X(\omega) \, dP(\omega)
 \end{aligned}
 \tag{4.12}$$

where $X(\omega) = \langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle(\omega)$. This implies that $X_{\varepsilon_n} \xrightarrow{\text{a.s.}} X$ and hence $X_{\varepsilon_n} \xrightarrow{D} X$. In other words

$$\begin{aligned}
 &\lim_{\varepsilon_n \rightarrow 0^+} \int_{\Pi_T} \psi(t, x) (\Psi_1(u_{\varepsilon_n}(t, x)) \Phi_2(u_{\varepsilon_n}(t, x)) - \Phi_1(u_{\varepsilon_n}(t, x)) \Psi_2(u_{\varepsilon_n}(t, x))) \, dx \, dt \\
 &\quad \stackrel{D}{=} \langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle.
 \end{aligned}$$

Let $G_\varepsilon(t, x) = (\Phi_1(u_\varepsilon(t, x)), \Psi_1(u_\varepsilon(t, x)))$ and $H_\varepsilon(t, x) = (-\Psi_2(u_\varepsilon(t, x)), \Phi_2(u_\varepsilon(t, x)))$. By the moment estimate (4.4), we see that the families $\{G_\varepsilon\}_{\varepsilon>0}$ and $\{H_\varepsilon\}_{\varepsilon>0}$ are stochastically bounded as $L^2(\Pi_T; \mathbb{R}^2)$ -valued random variables.

We now call upon [8, Lemma 4.18] and claim that $\{\partial_t \Phi_\varepsilon^i + \partial_x \Psi_\varepsilon^i\}_n$, where $\Phi_\varepsilon^i = \Phi_i(u_\varepsilon(\cdot, \cdot))$ and $\Psi_\varepsilon^i = \Psi(u_\varepsilon(\cdot, \cdot))$ and $i = 1, 2$; are tight sequences as $H^{-1}(\Pi_T)$ -valued random variables. This means both $\{\nabla \cdot G_{\varepsilon_n}\}_n$ and $\{\nabla \times H_{\varepsilon_n}\}_n$ are tight as sequences of $H^{-1}(\Pi_T)$ -valued random variables. In view of Lemma 4.3, we see that condition (2) of the div–curl lemma [8, Theorem A.2] holds. Therefore, one can apply the div–curl lemma and have

$$\begin{aligned} & \lim_{\varepsilon_n \rightarrow 0^+} \int_{\Pi_T} \psi(t, x) (\Psi_1(u_{\varepsilon_n}(t, x)) \Phi_2(u_{\varepsilon_n}(t, x)) - \Phi_1(u_{\varepsilon_n}(t, x)) \Psi_2(u_{\varepsilon_n}(t, x))) \, dx \, dt \\ & \stackrel{D}{=} \langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle. \end{aligned}$$

Thus, for every deterministic $\psi \in C_c^\infty(\Pi_T)$,

$$\langle \psi, \overline{\Psi_1 \Phi_2} - \overline{\Phi_1 \Psi_2} \rangle \stackrel{D}{=} \langle \psi, \overline{\Psi_1} \cdot \overline{\Phi_2} - \overline{\Phi_1} \cdot \overline{\Psi_2} \rangle. \quad \square$$

Proof of Lemma 4.4. Let $\phi \in C_c^\infty(\Pi_T)$ be nonnegative deterministic test function. Choose $\Phi_1(u) = u$ and $\Psi(u) = F(u) \equiv \Psi_1(u)$. Then $\Psi_2(u) = \int_0^u (F'(r))^2 \, dr$. Now apply Lemma 4.6 and arrive at

$$\langle \psi, \overline{F^2} - \overline{u \Psi_2} \rangle \stackrel{D}{=} \langle \psi, (\overline{F})^2 - \overline{u \cdot \Psi_2} \rangle. \tag{4.13}$$

Note that, by Schwartz inequality, for any $u \in \mathbb{R}$

$$(F(u) - F(\overline{u}(\theta)))^2 = \left(\int_{\overline{u}(\theta)}^u F'(v) \, dv \right)^2 \leq (u - \overline{u}(\theta)) (\Psi_2(u) - \Psi_2(\overline{u}(\theta))). \tag{4.14}$$

Integrating the inequality (4.14) against $\nu(\theta)(du)$, we have

$$\overline{F^2}(\theta) - 2\overline{F}(\theta)F(\overline{u}(\theta)) + (F(\overline{u}(\theta)))^2 \leq \overline{u \Psi_2}(\theta) - \overline{u}(\theta) \cdot \overline{\Psi_2}(\theta). \tag{4.15}$$

We now multiply (4.15) by $\psi(t, x)$ and integrate against $\mu(d\theta)$ (i.e. $dx \, dt \, dP(\omega)$) and obtain

$$\begin{aligned} & \int_{\Pi_T} \psi(t, x) E[(\overline{F} - F(\overline{u}))^2] \, dt \, dx \\ & \leq \int_{\Pi_T} \psi(t, x) E[(\overline{u \Psi_2} - \overline{u \cdot \Psi_2}) - (\overline{F^2} - (\overline{F})^2)] \, dt \, dx = 0 \quad \text{by (4.13)}. \end{aligned}$$

In other words

$$\int_{\Pi_T} \psi(t, x) E[(\bar{F} - F(\bar{u}))^2] dt dx = 0, \tag{4.16}$$

which implies

$$\int_{\Pi_T} \psi(t, x) \bar{F}(\omega; t, x) dx dt = \int_{\Pi_T} \psi(t, x) F(\bar{u}(\omega; t, x)) dx dt \quad \text{almost surely.} \tag{4.17}$$

In view of (4.17) and (4.13), one has

$$\begin{aligned} & \int_{\Pi_T} \psi(t, x) E \left[\int_{u \in \mathbb{R}} (F(u) - F(\bar{u}(\omega; t, x)))^2 \nu(\omega; t, x)(du) \right] dt dx \\ &= \int_{\Pi_T} \psi(t, x) E [\bar{F}^2 - (\bar{F})^2] dt dx \\ &= \int_{\Pi_T} \psi(t, x) E [(\bar{u}\bar{\Psi}_2 - \bar{u}.\bar{\Psi}_2)] dt dx \\ &= \int_{\Pi_T} \psi(t, x) E \left[\int_{u \in \mathbb{R}} ((u - \bar{u}(\omega; t, x))(\Psi_2(u) - \Psi_2(\bar{u}(\omega; t, x)))) \nu(\omega; t, x)(du) \right] dt dx. \end{aligned}$$

We now invoke (4.14) and arbitrariness of ψ to conclude that for μ -almost all $\theta \in \Theta$ and every $u \in \text{support}(\nu(\theta))$, we must have

$$(F(u) - F(\bar{u}(\theta)))^2 = (u - \bar{u}(\theta))(\Psi_2(u) - \Psi_2(\bar{u}(\theta))). \tag{4.18}$$

To this end we recall the condition for equality in Schwartz inequality and conclude that (4.18) is possible only if F' is constant between u and $\bar{u}(\theta)$. This is an impossibility if u is different from $\bar{u}(\theta)$, thanks to (A.4). Therefore $\nu(\theta)$ is a probability measure on \mathbb{R} which is supported at the point $\bar{u}(\theta)$ for μ -almost every $\theta \in \Theta$. In other words, (4.9) holds. \square

4.5. Existence of entropy solution

In view of the results and analysis above, it is now routine to show that $\bar{u}(\omega; t, x)$ satisfies the stochastic entropy condition. From here onwards, will simply drop ω and write $\bar{u}(t, x)$ in place of $\bar{u}(\omega; t, x)$. We begin by fixing a nonnegative test function $\psi \in C_c^\infty([0, \infty) \times \mathbb{R})$, $B \in \mathcal{F}_T$ and convex entropy pair (β, ζ) .

Assume that ζ_ϵ be the entropy flux with flux function F_ϵ which would approximate ζ . Now apply Itô's formula on (4.1) followed by Itô product rule (as in (2.2)) and then multiply by $\psi(t, x)\mathbf{1}_B$ and integrate to obtain

$$\begin{aligned}
 0 \leq & E \left[\mathbf{1}_B \int_{\mathbb{R}} \beta(u_0^{\varepsilon_n}(x)) \psi(0, x) dx \right] - \varepsilon E \left[\mathbf{1}_B \int_{\Pi_T} \beta'(u_{\varepsilon_n}(t, x)) \nabla u_{\varepsilon_n}(t, x) \cdot \nabla \psi(t, x) dx dt \right] \\
 & + E \left[\mathbf{1}_B \int_{\Pi_T} (\beta(u_{\varepsilon_n}(t, x)) \partial_t \psi(t, x) + \zeta_{\varepsilon_n}(u_{\varepsilon_n}(t, x)) \cdot \nabla \psi(t, x)) dt dx \right] \\
 & + E \left[\mathbf{1}_B \int_{\Pi_T} \sigma_{\varepsilon_n}(x, u_{\varepsilon_n}(t, x)) \beta'(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dW(t) \right] \\
 & + \frac{1}{2} E \left[\mathbf{1}_B \int_{\Pi_T} \sigma_{\varepsilon_n}^2(x, u_{\varepsilon_n}(t, x)) \beta''(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dt \right] \tag{4.19}
 \end{aligned}$$

With the help of uniform moment estimates and (4.3); (4.19) gives

$$\begin{aligned}
 0 \leq & E \left[\mathbf{1}_B \int_{\mathbb{R}} \beta(u_0^{\varepsilon_n}(x)) \psi(0, x) dx \right] - \varepsilon E \left[\mathbf{1}_B \int_{\Pi_T} \beta'(u_{\varepsilon_n}(t, x)) \nabla u_{\varepsilon_n}(t, x) \cdot \nabla \psi(t, x) dx dt \right] \\
 & + E \left[\mathbf{1}_B \int_{\Pi_T} (\beta(u_{\varepsilon_n}(t, x)) \partial_t \psi(t, x) + \zeta(u_{\varepsilon_n}(t, x)) \cdot \nabla \psi(t, x)) dt dx \right] \\
 & + E \left[\mathbf{1}_B \int_{\Pi_T} \sigma(x, u_{\varepsilon_n}(t, x)) \beta'(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dW(t) \right] \\
 & + \frac{1}{2} E \left[\mathbf{1}_B \int_{\Pi_T} \sigma^2(x, u_{\varepsilon_n}(t, x)) \beta''(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dt \right] + \mathcal{O}(\varepsilon_n) \tag{4.20}
 \end{aligned}$$

All that is left now is to justify passage to the limit $\varepsilon_n \rightarrow 0$ in (4.20). In view of the estimate (4.5), it holds that

$$\lim_{\varepsilon_n \rightarrow 0} \varepsilon_n E \left[\mathbf{1}_B \int_{\Pi_T} \beta'(u_{\varepsilon_n}(t, x)) \nabla u_{\varepsilon_n}(t, x) \cdot \nabla \psi(t, x) dx dt \right] = 0. \tag{4.21}$$

Furthermore, it follows from straightforward computation that

$$\lim_{\varepsilon_n \rightarrow 0} E \left[\mathbf{1}_B \int_{\mathbb{R}} \beta(u_0^{\varepsilon_n}(x)) \psi(0, x) dx \right] = E \left[\mathbf{1}_B \int_{\mathbb{R}} \beta(u_0(x)) \psi(0, x) dx \right]. \tag{4.22}$$

Note that $\mathbf{1}_B(\omega)$ may not be Σ -measurable, but we can adapt the technique as in the derivation of (4.12) in the proof of Lemma 4.6 and apply Lemmas 4.3 and 4.5 to have

$$\begin{aligned} & \lim_{\varepsilon_n \rightarrow 0} E \left[\mathbf{1}_B \int_{\Pi_T} (\beta(u_{\varepsilon_n}(t, x)) \partial_t \psi(t, x) + \zeta(u_{\varepsilon_n}(t, x)) \cdot \nabla \psi(t, x)) dt dx \right] \\ &= E \left[\mathbf{1}_B \int_{\Pi_T} (\beta(\bar{u}(t, x)) \partial_t \psi(t, x) + \zeta(\bar{u}(t, x)) \cdot \nabla \psi(t, x)) dt dx \right] \end{aligned} \tag{4.23}$$

and

$$\begin{aligned} & \lim_{\varepsilon_n \rightarrow 0} \frac{1}{2} E \left[\mathbf{1}_B \int_{\Pi_T} \sigma^2(x, u_{\varepsilon_n}(t, x)) \beta''(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dt \right] \\ &= \frac{1}{2} E \left[\mathbf{1}_B \int_{\Pi_T} \sigma^2(x, \bar{u}(t, x)) \beta''(\bar{u}(t, x)) \psi(t, x) dx dt \right]. \end{aligned} \tag{4.24}$$

Now passage to the limit in the martingale term requires some additional reasoning. Let $\Gamma = \Omega \times [0, T]$, $\mathcal{G} = \mathcal{P}_T$ and $\varsigma = P \otimes \lambda_t$. The space $L^2((\Gamma, \mathcal{G}, \varsigma); \mathbb{R})$ represents the space of square integrable predictable integrands for Itô integrals with respect to $W(t)$. Moreover, by Itô isometry and martingale representation theorem, it follows that Itô integral defines isometry between two Hilbert spaces $L^2((\Gamma, \mathcal{G}, \varsigma); \mathbb{R})$ and $L^2((\Omega, \mathcal{F}_T); \mathbb{R})$. In other words, if \mathcal{I} denotes the Itô integral operator and $\{X_n\}_n$ be sequence in $L^2((\Gamma, \mathcal{G}, \varsigma); \mathbb{R})$ weakly converging to X ; then $\mathcal{I}(X_n)$ will converge weakly to $\mathcal{I}(X)$ in $L^2((\Omega, \mathcal{F}_T); \mathbb{R})$.

We again apply [Lemmas 4.3 and 4.5](#) and conclude that for any $h(t) \in L^2((\Gamma, \mathcal{G}, \varsigma); \mathbb{R})$

$$\begin{aligned} & \lim_{\varepsilon_n \rightarrow 0} E \left[\int_0^T \int_{\mathbb{R}} \sigma(x, u_{\varepsilon_n}(t, x)) \beta'(u_{\varepsilon_n}(t, x)) h(t) \psi(t, x) dx dt \right] \\ &= E \left[\int_0^T \int_{\mathbb{R}} \sigma(x, \bar{u}(t, x)) \beta'(\bar{u}(t, x)) h(t) \psi(t, x) dx dt \right]. \end{aligned}$$

Hence, if we denote $X_n = \int_{\mathbb{R}} \sigma(x, u_{\varepsilon_n}(t, x)) \beta'(u_{\varepsilon_n}(t, x)) \psi(t, x) dx$ and $X = \int_{\mathbb{R}} \sigma(x, \bar{u}(t, x)) \beta'(\bar{u}(t, x)) h(t) \psi(t, x) dx$, then X_n converges weakly to X in $L^2((\Gamma, \mathcal{G}, \varsigma); \mathbb{R})$. Therefore $\mathcal{I}(X_n)$ will converge weakly to $\mathcal{I}(X)$ in $L^2((\Omega, \mathcal{F}_T); \mathbb{R})$. In other words, the following lemma holds.

Lemma 4.7. *For every $B \in \mathcal{F}_T$*

$$\begin{aligned} & \lim_{\varepsilon_n \rightarrow 0} E \left[\mathbf{1}_B \int_0^T \int_{\mathbb{R}} \sigma(x, u_{\varepsilon_n}(t, x)) \beta'(u_{\varepsilon_n}(t, x)) \psi(t, x) dx dW(t) \right] \\ &= E \left[\mathbf{1}_B \int_0^T \int_{\mathbb{R}} \sigma(x, \bar{u}(t, x)) \beta'(\bar{u}(t, x)) \psi(t, x) dx dW(t) \right] \end{aligned}$$

Now simply combine (4.21)–(4.24) along with Lemma 4.7 and pass to the limit $\varepsilon_n \downarrow 0$ in (4.20) and obtain

$$\begin{aligned}
 0 \leq & E \left[\mathbf{1}_B \int_{\mathbb{R}} \beta(u_0(x)) \psi(0, x) dx \right] + E \left[\mathbf{1}_B \int_{\Pi_T} \beta(\bar{u}(t, x)) \partial_t \psi(t, x) dt dx \right] \\
 & + E \left[\mathbf{1}_B \int_{\Pi_T} \zeta(\bar{u}(t, x)) \cdot \nabla \psi(t, x) dt dx \right] \\
 & + \frac{1}{2} E \left[\mathbf{1}_B \int_{\Pi_T} \sigma^2(x, \bar{u}(t, x)) \beta''(\bar{u}(t, x)) \psi(t, x) dx dt \right] \\
 & + E \left[\mathbf{1}_B \int_0^T \int_{\mathbb{R}} \sigma(x, \bar{u}(t, x)) \beta'(\bar{u}(t, x)) \psi(t, x) dx dW(t) \right] \tag{4.25}
 \end{aligned}$$

Finally, we now combine the results above and claim that $\bar{u}(t, x)$ is a stochastic entropy solution of (1.1).

Lemma 4.8. *The function $\bar{u}(t, x)$ is an entropy solution of (1.1).*

Proof. The predictability of $\bar{u}(t, x)$ and necessary moment estimates are derived in Lemma 4.4. Since (4.25) is satisfied for all $B \in \mathcal{F}_T$, we must have

$$\begin{aligned}
 & \int_{\mathbb{R}} \beta(u_0(x)) \psi(0, x) dx + \int_{\Pi_T} \beta(\bar{u}(t, x)) \partial_t \psi(t, x) dt dx \\
 & + \int_{\Pi_T} \zeta(\bar{u}(t, x)) \cdot \nabla \psi(t, x) dt dx + \frac{1}{2} \int_{\Pi_T} \sigma^2(x, \bar{u}(t, x)) \beta''(\bar{u}(t, x)) \psi(t, x) dx dt \\
 & + \int_0^T \int_{\mathbb{R}} \sigma(x, \bar{u}(t, x)) \beta'(\bar{u}(t, x)) \psi(t, x) dx dW(t) \geq 0 \quad P\text{-a.s.}
 \end{aligned}$$

In other words, \bar{u} satisfies the stochastic entropy condition. \square

5. Existence of strong entropy solution

In this section we establish that the vanishing viscosity limit $v(t, x) = \bar{u}(t, x)$ is indeed a strong entropy solution. To this end, let $\tilde{u}(t) = \tilde{u}(t, x)$ be an \mathcal{F}_t -predictable and $L^2(\mathbb{R})$ -valued process with

$$\sup_{0 \leq t \leq T} E[\|\tilde{u}(t)\|_p^2] < \infty, \quad \text{for all } T > 0, p = 2, 4, \dots \tag{5.1}$$

Furthermore, let β be a smooth convex function approximating the absolute value in \mathbb{R} and $\psi \in C_c^\infty([0, \infty) \times \mathbb{R})$ be a nonnegative test function. For constants $\delta > 0, \delta_0 > 0$, define

$$\phi_{\delta, \delta_0}(t, x, s, y) = \rho_{\delta_0}(t - s) \varrho_\delta(x - y) \psi(s, y).$$

Lemma 5.1. *For each $T > 0$, there exists a deterministic function $A(\delta, \delta_0)$ such that*

$$\begin{aligned} & E \left[\int_0^T \int_y^T \int_0^T \int_x^T \sigma(x, \tilde{u}(r, x)) \beta'(\tilde{u}(r, x) - v) \phi_{\delta, \delta_0}(r, x, s, y) dx dW(r) \Big|_{v=v(s, y)} dy ds \right] \\ & \leq -E \left[\int_{\Pi_T} \int_{\Pi_T} \sigma(x, \tilde{u}(r, x)) \sigma(y, v(r, y)) \beta''(\tilde{u}(r, x) - v(r, y)) \right. \\ & \quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] + A(\delta, \delta_0). \end{aligned}$$

Furthermore, for fixed δ, ψ and β , the function $A(\delta, \delta_0)$ has the property that

$$\lim_{\delta_0 \rightarrow 0} A(\delta, \delta_0) = 0.$$

A significant part of the proof is built on ideas borrowed from [8], and the proof requires some preparation. Given a nonnegative test function $\phi \in C_c^\infty(\Pi_\infty \times \Pi_\infty)$ and $\beta \in C^\infty(\mathbb{R})$ such that $\beta', \beta'' \in C_b(\mathbb{R})$, define

$$J[\beta, \phi](s; y, v) := \int_0^T \int_x^T \sigma(x, \tilde{u}(r, x)) \beta(\tilde{u}(r, x) - v) \phi(r, x, s, y) dx dW(r)$$

where $0 \leq s \leq T, (y, v) \in \mathbb{R} \times \mathbb{R}$.

Since the test function ψ has compact support, there exists $c_\phi > 0$ such that $J[\beta, \phi](s; y, v) = 0$ if $|y| > c_\phi$ and $0 \leq s \leq T$.

Lemma 5.2. *The following identities hold:*

$$\begin{aligned} \partial_v J[\beta, \phi](s; y, v) &= J[-\beta', \phi](s; y, v) \\ \partial_y J[\beta, \phi](s; y, v) &= J[\beta, \partial_y \phi](s; y, v). \end{aligned}$$

Proof. The proof is similar to the that of Leibniz integral rule. \square

Lemma 5.3. *Let $\beta \in C^\infty(\mathbb{R})$ be function such that $\beta', \beta'' \in C_c^\infty(\mathbb{R})$. Then there exists a constant $C = C(\beta', \psi)$ such that*

$$\sup_{0 \leq s \leq T} (E \| J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot) \|_{L^\infty(\mathbb{R} \times \mathbb{R})}^2) \leq \frac{C(\beta', \psi)}{\delta_0^{\frac{3}{2}}}. \tag{5.2}$$

Proof. We intend to establish (5.2) with the help of appropriate Sobolev embedding theorem. To this end, we begin with

$$\begin{aligned}
 & E \left[\left\| J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot) \right\|_4^4 \right] \\
 &= E \left[\int_v \int_y |J[\beta, \phi_{\delta, \delta_0}](s; y, v)|^4 dy dv \right] \\
 &= E \left[\int_v \int_y \left| \int_0^T \int_x \sigma(x, \tilde{u}(r, x)) \beta(\tilde{u}(r, x) - v) \right. \right. \\
 &\quad \left. \left. \times \rho_{\delta_0}(r - s) \varrho_{\delta}(x - y) \psi(s, y) dx dW(r) \right|^4 dy dv \right] \\
 &\quad \text{(by BDG inequality)} \\
 &\leq C \int_v \int_y E \left[\left(\int_0^T \left| \int_x \sigma(x, \tilde{u}(r, x)) \beta(\tilde{u}(r, x) - v) \right. \right. \right. \\
 &\quad \left. \left. \times \rho_{\delta_0}(r - s) \varrho_{\delta}(x - y) \psi(s, y) dx \right|^2 dr \right)^2 \right] dy dv \\
 &\leq C \int_v \int_{|y| < C_{\psi}} E \left[\left(\int_0^T \int_x \sigma^2(x, \tilde{u}(r, x)) \beta^2(\tilde{u}(r, x) - v) \right. \right. \\
 &\quad \left. \left. \times \rho_{\delta_0}^2(r - s) \varrho_{\delta}^2(x - y) \psi^2(s, y) dx dr \right)^2 \right] dy dv \\
 &\leq C \int_v \int_{|y| < C_{\psi}} E \left[\int_0^T \int_x \sigma^4(x, \tilde{u}(r, x)) \beta^4(\tilde{u}(r, x) - v) \right. \\
 &\quad \left. \times \rho_{\delta_0}^4(r - s) \varrho_{\delta}^4(x - y) \psi^4(s, y) dx dr \right] dy dv \\
 &\leq CE \left[\int_{|y| < C_{\psi}} \int_0^T \int_x \int_{|v| \leq C_{\beta} + |\tilde{u}(r, x)|} \sigma^4(x, \tilde{u}(r, x)) \|\beta'\|_{\infty}^4 \right. \\
 &\quad \left. \times \rho_{\delta_0}^4(r - s) \varrho_{\delta}^4(x - y) \|\psi\|_{\infty}^4 dv dx dr dy \right] \\
 &\leq C(\beta, \psi) E \left[\int_0^T \int_x g^4(x) (1 + |\tilde{u}(r, x)|^4) \right]
 \end{aligned}$$

$$\begin{aligned}
 & \times \left(C_\beta + (1 + |\tilde{u}(r, x)|) \right) \rho_{\delta_0}^4(r - s) dx dr \Big] \\
 & \leq C(\beta, \psi) E \left[\int_0^T \int_x^T g^4(x) (1 + |\tilde{u}(r, x)|^5) \rho_{\delta_0}^4(r - s) dx dr \right] \\
 & \leq C(\beta, \psi) \int_0^T (1 + E \|\tilde{u}(r, \cdot)\|_5^5) \rho_{\delta_0}^4(r - s) dr \\
 & \leq C(\beta, \psi) \left(1 + \sup_{0 \leq r \leq T} E \|\tilde{u}(r, \cdot)\|_5^5 \right) \int_0^T \rho_{\delta_0}^4(r - s) dr \\
 & \leq C(\beta, \psi) \left(1 + \sup_{0 \leq r \leq T} E \|\tilde{u}(r, \cdot)\|_5^5 \right) \|\rho_{\delta_0}\|_\infty^3 \int_0^T \rho_{\delta_0}(r - s) dr \\
 & \leq \frac{C(\beta, \psi) (1 + \sup_{0 \leq r \leq T} E \|\tilde{u}(r, \cdot)\|_5^5)}{\delta_0^3}. \tag{5.3}
 \end{aligned}$$

Similarly, we have

$$E \left[\|\partial_v J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_4^4 \right] \leq \frac{C(\beta'', \psi)}{\delta_0^3} \tag{5.4}$$

$$E \left[\|\partial_y J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_4^4 \right] \leq \frac{C(\beta', \partial_y \psi)}{\delta_0^3} \tag{5.5}$$

Therefore, by (5.3), (5.4), and (5.5),

$$E \left[\|J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{W^{1,4}(\mathbb{R} \times \mathbb{R})}^4 \right] \leq \frac{C(\beta', \psi)}{\delta_0^3}.$$

We simply now use Sobolev embedding along with Cauchy–Schwartz inequality and conclude

$$\sup_{0 \leq s \leq T} (E \left[\|J[\beta, \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})}^2 \right]) \leq \frac{C(\beta', \psi)}{\delta_0^{\frac{3}{2}}}. \quad \square \tag{5.6}$$

Our primary aim is to estimate the expected value of $J[\beta', \phi_{\delta, \delta_0}](s; y, v(s, y))$, which we do by estimating the same for $J[\beta', \phi_{\delta, \delta_0}](s; y, u_\varepsilon(s, y))$ and then passing to the limit. Note that if we directly substitute $v = v(s, y)$ in the formula for $J[\beta', \phi_{\delta, \delta_0}]$, the integrand would no-longer be nonanticipative, and therefore standard methods Itô integrals would no-longer apply. To work around this problem, we proceed as follows.

Let $\{\rho_l\}_{l>0}$ be the standard sequence of mollifiers in \mathbb{R} and define

$$Z_{\varepsilon,\delta,\delta_0,l} := \int_{\mathbb{R}} \int_{\Pi_T} J[\beta', \phi_{\delta,\delta_0}](s; y, v) \rho_l(u_\varepsilon(s, y) - v) dy ds dv. \tag{5.7}$$

We would like to find an upper bound on $E[Z_{\varepsilon,\delta,\delta_0,l}]$ as $l, \varepsilon \rightarrow 0$. To this end, we claim that for two constants $T_1, T_2 \geq 0$ with $T_1 < T_2$,

$$E \left[X_{T_1} \int_{T_1}^{T_2} J(t) dW(t) \right] = 0 \tag{5.8}$$

where J is a predictable integrand and $X(\cdot)$ is an adapted process. The conclusion (5.8) follows trivially if J is a simple predictable integrand. The general case could be argued by standard approximation technique.

If necessary, we extend the process $u_\varepsilon(\cdot, y)$ for negative time simply by $u_\varepsilon(s, y) = u_\varepsilon(0, y)$ if $s < 0$. With this convention, it follows from (5.8) that

$$E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta', \phi_{\delta,\delta_0}](s; y, v) \rho_l(u_\varepsilon(s - \delta_0, y) - v) dy ds dv \right] = 0.$$

Hence

$$E[Z_{\varepsilon,\delta,\delta_0,l}] = E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta', \phi_{\delta,\delta_0}](s; y, v) (\rho_l(u_\varepsilon(s, y) - v) - \rho_l(u_\varepsilon(s - \delta_0, y) - v)) dy ds dv \right]. \tag{5.9}$$

Given $y \in \mathbb{R}$, $u_\varepsilon(\cdot, y)$ satisfies

$$du_\varepsilon(s, y) = -\operatorname{div} F_\varepsilon(u_\varepsilon(s, y)) ds + \varepsilon \Delta u_\varepsilon(s, y) ds + \sigma_\varepsilon(y, u_\varepsilon(s, y)) dW(s).$$

Next, apply Itô-formula and obtain

$$\begin{aligned} & \rho_l(u_\varepsilon(s, y) - v) - \rho_l(u_\varepsilon(s - \delta_0, y) - v) \\ &= \int_{s-\delta_0}^s \rho'_l(u_\varepsilon(\tau, y) - v) (-\operatorname{div} F_\varepsilon(u_\varepsilon(\tau, y)) + \varepsilon \Delta u_\varepsilon(\tau, y)) d\tau \\ & \quad + \int_{s-\delta_0}^s \sigma_\varepsilon(y, u_\varepsilon(\tau, y)) \rho'_l(u_\varepsilon(\tau, y) - v) dW(\tau) \\ & \quad + \frac{1}{2} \int_{s-\delta_0}^s |\sigma_\varepsilon(y, u_\varepsilon(\tau, y))|^2 \rho''_l(u_\varepsilon(\tau, y) - v) d\tau \end{aligned}$$

$$\begin{aligned}
 &= -\frac{\partial}{\partial v} \left[\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) (-\operatorname{div} F_\varepsilon(u_\varepsilon(\tau, y)) + \varepsilon \Delta u_\varepsilon(\tau, y)) d\tau \right. \\
 &\quad + \int_{s-\delta_0}^s \sigma_\varepsilon(y, u_\varepsilon(\tau, y)) \rho_l(u_\varepsilon(\tau, y) - v) dW(\tau) \\
 &\quad \left. + \frac{1}{2} \int_{s-\delta_0}^s \sigma_\varepsilon^2(y, u_\varepsilon(\tau, y)) \rho_l'(u_\varepsilon(\tau, y) - v) d\tau \right].
 \end{aligned}$$

From (5.9), we now have

$$\begin{aligned}
 &E[Z_{\varepsilon, \delta, \delta_0, l}] \\
 &= E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta', \phi_{\delta, \delta_0}](s; y, v) \left\{ -\frac{\partial}{\partial v} \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) (-\operatorname{div} F_\varepsilon(u_\varepsilon(\tau, y)) \right. \right. \right. \\
 &\quad \left. \left. + \varepsilon \Delta u_\varepsilon(\tau, y)) d\tau + \int_{s-\delta_0}^s \sigma_\varepsilon(y, u_\varepsilon(\tau, y)) \rho_l(u_\varepsilon(\tau, y) - v) dW(\tau) \right. \right. \\
 &\quad \left. \left. + \frac{1}{2} \int_{s-\delta_0}^s |\sigma_\varepsilon(y, u_\varepsilon(\tau, y))|^2 \rho_l'(u_\varepsilon(\tau, y) - v) d\tau \right\} dy ds dv \right]
 \end{aligned}$$

(by the Itô-product rule and Lemma 5.2)

$$\begin{aligned}
 &= E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta'', \phi_{\delta, \delta_0}](s; y, v) \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) \operatorname{div} F_\varepsilon(u_\varepsilon(\tau, y)) d\tau \right) dy ds dv \right] \\
 &\quad - E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta'', \phi_{\delta, \delta_0}](s; y, v) \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) \varepsilon \Delta u_\varepsilon(\tau, y) d\tau \right) dy ds dv \right] \\
 &\quad - E \left[\int_{\Pi_T} \int_x \int_{s-\delta_0}^s \left(\int_{\mathbb{R}} \beta''(\tilde{u}(r, x) - v) \rho_l(u_\varepsilon(r, y) - v) dv \right) \sigma(x, \tilde{u}(r, x)) \right. \\
 &\quad \left. \times \sigma_\varepsilon(y, u_\varepsilon(r, y)) \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] \\
 &\quad + \frac{1}{2} E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta''', \phi_{\delta, \delta_0}](s; y, v) \right. \\
 &\quad \left. \times \left\{ \int_{s-\delta_0}^s \sigma_\varepsilon^2(y, u_\varepsilon(\tau, y)) \rho_l(u_\varepsilon(\tau, y) - v) d\tau \right\} dy ds dv \right]
 \end{aligned}$$

$$\equiv A_1^{l,\varepsilon}(\delta, \delta_0) + A_2^{l,\varepsilon}(\delta, \delta_0) + B^{\varepsilon,l}(\delta, \delta_0) + A_3^{l,\varepsilon}(\delta, \delta_0) \tag{5.10}$$

where

$$A_1^{l,\varepsilon}(\delta, \delta_0) = E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta'', \phi_{\delta, \delta_0}](s; y, v) \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) \operatorname{div} F_\varepsilon(u_\varepsilon(\tau, y)) d\tau \right) dy ds dv \right]$$

$$A_2^{l,\varepsilon}(\delta, \delta_0) = -E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta'', \phi_{\delta, \delta_0}](s; y, v) \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) \varepsilon \Delta u_\varepsilon(\tau, y) d\tau \right) dy ds dv \right]$$

$$B^{l,\varepsilon}(\delta, \delta_0) = -E \left[\int_{\Pi_T} \int_x \int_{s-\delta_0}^s \left(\int_{\mathbb{R}} \beta''(\tilde{u}(r, x) - v) \rho_l(u_\varepsilon(r, y) - v) dv \right) \sigma(x, \tilde{u}(r, x)) \times \sigma_\varepsilon(y, u_\varepsilon(r, y)) \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right]$$

$$A_3^{l,\varepsilon}(\delta, \delta_0) = \frac{1}{2} E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta''', \phi_{\delta, \delta_0}](s; y, v) \left\{ \int_{s-\delta_0}^s \sigma_\varepsilon^2(y, u_\varepsilon(\tau, y)) \rho_l(u_\varepsilon(\tau, y) - v) d\tau \right\} dy ds dv \right]$$

Let $A_1^\varepsilon(\delta, \delta_0) := \lim_{l \rightarrow 0} A_1^{l,\varepsilon}(\delta, \delta_0)$ and $A_1(\delta, \delta_0) = \limsup_{\varepsilon \downarrow 0} |A_1^\varepsilon(\delta, \delta_0)|$.

Lemma 5.4. *It holds that*

$$A_1(\delta, \delta_0) \rightarrow 0 \quad \text{as } \delta_0 \rightarrow 0. \tag{5.11}$$

Proof. We start by letting

$$G_\varepsilon(u, v) = \int_0^v \beta''(u - r) F'_\varepsilon(r) dr \quad \text{for } u, v \in \mathbb{R}.$$

It is straightforward to check that there is a positive integer p such that

$$\sup_{\varepsilon > 0} |G_\varepsilon(u, v)| \leq C_\beta (1 + |u|^p) \quad \text{for all } u, v \in \mathbb{R}. \tag{5.12}$$

Let

$$X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) := \int_0^T \int_x \sigma(x, \tilde{u}(r, x)) G_\varepsilon(\tilde{u}(r, x), v) \phi_{\delta,\delta_0}(r, x; s, y) dx dW(r)$$

Once again by the same arguments as in [Lemma 5.2](#), it holds that

$$\begin{aligned} \partial_v X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) &= \int_0^T \int_x \sigma(x, \tilde{u}(r, x)) \partial_v G_\varepsilon(\tilde{u}(r, x), v) \phi_{\delta,\delta_0}(r, x; s, y) dx dW(r) \\ \partial_y X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) &= X_\varepsilon[\partial_y \phi_{\delta,\delta_0}](s; y, v). \end{aligned}$$

Moreover, we can argue as in [Lemma 5.3](#) and find a constant $C = C(\beta, \psi)$ such that

$$\sup_{\varepsilon > 0} \sup_{0 \leq s \leq T} (E[\|X_\varepsilon[\partial_y \phi_{\delta,\delta_0}](s; \cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})}^2]) \leq \frac{C(\beta, \psi)}{\delta_0^{\frac{3}{2}}}. \tag{5.13}$$

Claim.

$$A_1^\varepsilon(\delta, \delta_0) = -E \left[\int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon[\partial_y \phi_{\delta,\delta_0}](s; y, u_\varepsilon(\tau, y)) d\tau ds dy \right]. \tag{5.14}$$

Proof of the claim. We repeatedly use integration by parts and have

$$\begin{aligned} &\int_v \int_{\Pi_T} J[\beta'', \phi_{\delta,\delta_0}](s, y, v) \left(\int_{s-\delta_0}^s \rho_l(u_\varepsilon(\tau, y) - v) F'_\varepsilon(v) \partial_y u_\varepsilon(\tau, y) d\tau \right) ds dy dv \\ &= \int_v \int_{\Pi_T} \int_{s-\delta_0}^s \int_0^T \int_x \sigma(x, \tilde{u}(r, x)) \beta''(\tilde{u}(r, x) - v) F'_\varepsilon(v) \phi_{\delta,\delta_0}(r, x; s, y) \\ &\quad \times \rho_l(u_\varepsilon(\tau, y) - v) \partial_y u_\varepsilon(\tau, y) dW(r) dx d\tau ds dy dv \\ &= \int_v \int_{\Pi_T} \int_{s-\delta_0}^s \partial_v X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) \rho_l(u_\varepsilon(\tau, y) - v) \partial_y u_\varepsilon(\tau, y) d\tau ds dy dv \\ &= \int_v \int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) \rho'_l(u_\varepsilon(\tau, y) - v) \partial_y u_\varepsilon(\tau, y) d\tau ds dy dv \\ &= \int_v \int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) \partial_y \rho_l(u_\varepsilon(\tau, y) - v) d\tau ds dy dv \\ &= - \int_v \int_{\Pi_T} \int_{s-\delta_0}^s \partial_y X_\varepsilon[\phi_{\delta,\delta_0}](s; y, v) \rho_l(u_\varepsilon(\tau, y) - v) d\tau ds dy dv \end{aligned}$$

$$= - \int_v \int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon [\partial_y \phi_{\delta, \delta_0}] (s; y, v) \rho_l (u_\varepsilon (\tau, y) - v) \, d\tau \, ds \, dy \, dv. \tag{5.15}$$

We simply let $l \rightarrow 0$ in both sides of (5.15) and obtain

$$\begin{aligned} & \int_{\Pi_T} \int_{s-\delta_0}^s J[\beta'', \phi_{\delta, \delta_0}] (s; y, u_\varepsilon (\tau, y)) \operatorname{div}_y F_\varepsilon (u_\varepsilon (\tau, y)) \, d\tau \, ds \, dy \\ &= - \int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon [\partial_y \phi_{\delta, \delta_0}] (s; y, u_\varepsilon (\tau, y)) \, d\tau \, ds \, dy. \end{aligned} \tag{5.16}$$

We take expectation in both sides of (5.16) and the claim follows. \square

Now

$$\begin{aligned} \limsup_{\varepsilon \downarrow 0} |A_1^\varepsilon (\delta, \delta_0)| &= \limsup_{\varepsilon \downarrow 0} \left| E \left[\int_{\Pi_T} \int_{s-\delta_0}^s X_\varepsilon [\partial_y \phi_{\delta, \delta_0}] (s; y, u_\varepsilon (\tau, y)) \, d\tau \, ds \, dy \right] \right| \\ &\leq C \delta_0 \sup_{0 \leq s \leq T} \sup_{\varepsilon > 0} E \left[\| X_\varepsilon [\partial_y \phi_{\delta, \delta_0}] (s; \cdot, \cdot) \|_\infty \right] \\ &\leq C \delta_0 \sup_{0 \leq s \leq T} \sup_{\varepsilon > 0} \left(E \left[\| X_\varepsilon [\partial_y \phi_{\delta, \delta_0}] (s; \cdot, \cdot) \|_\infty^2 \right] \right)^{\frac{1}{2}} \\ &\leq C \delta_0 \frac{C(\beta, \phi)}{\delta_0^{\frac{3}{4}}} \\ &\leq C_1 (\beta, \phi) \delta_0^{\frac{1}{4}}. \end{aligned}$$

In other words, $A_1 (\delta, \delta_0) \leq C_1 (\beta, \phi) \delta_0^{\frac{1}{4}}$, and therefore

$$A_1 (\delta, \delta_0) \rightarrow 0 \quad \text{as } \delta_0 \rightarrow 0. \quad \square$$

Next, we define

$$A_2 (\delta, \delta_0) := \limsup_{\varepsilon \downarrow 0} |A_2^\varepsilon (\delta, \delta_0)| \quad \text{where } A_2^\varepsilon (\delta, \delta_0) := \lim_{l \rightarrow 0} A_2^{l, \varepsilon} (\delta, \delta_0) \tag{5.17}$$

Lemma 5.5. *It holds that*

$$A_2 (\delta, \delta_0) \rightarrow 0 \quad \text{as } \delta_0 \rightarrow 0. \tag{5.18}$$

Proof. From the definition of $A_2^{\varepsilon}(\delta, \delta_0)$, it follows that

$$A_2^{\varepsilon}(\delta, \delta_0) := \lim_{t \rightarrow \infty} A_2^{t, \varepsilon}(\delta, \delta_0) = -E \left[\int_{\Pi_T} \int_{s-\delta_0}^s J[\beta'', \phi_{\delta, \delta_0}](s; y, u_{\varepsilon}(\tau, y)) \varepsilon \Delta u_{\varepsilon}(\tau, y) d\tau ds dy \right].$$

Hence, by chain rule and integration by parts,

$$\begin{aligned} A_2^{\varepsilon}(\delta, \delta_0) &= E \left[\int_{\Pi_T} \int_{s-\delta_0}^s \int_0^T \int_x \varepsilon \sigma(x, \tilde{u}(r, x)) \beta'(\tilde{u}(r, x)) \right. \\ &\quad \left. - u_{\varepsilon}(\tau, y) \partial_{yy} \phi_{\delta, \delta_0}(r, x; s, y) dx dW(r) d\tau ds dy \right] \\ &\quad - E \left[\int_{\Pi_T} \int_{s-\delta_0}^s J[\beta''', \phi_{\delta, \delta_0}](s; y, u_{\varepsilon}(\tau, y)) \varepsilon |\nabla_y u_{\varepsilon}(\tau, y)|^2 d\tau ds dy \right] \\ &\equiv I_1^{\varepsilon} + I_2^{\varepsilon}. \end{aligned}$$

Now, we use the uniform moment estimates and conclude that

$$\limsup_{\varepsilon \downarrow 0} |I_1^{\varepsilon}| = \lim_{\varepsilon \downarrow 0} |I_1^{\varepsilon}| = 0. \tag{5.19}$$

Thus

$$\limsup_{\varepsilon \downarrow 0} |A_2^{\varepsilon}(\delta, \delta_0)| \leq \limsup_{\varepsilon \downarrow 0} |I_2^{\varepsilon}|, \tag{5.20}$$

and need of the hour is to estimate I_2^{ε} . Define

$$M_{s-\delta_0}^t[\beta''', \psi, \delta](y, v) = \int_{s-\delta_0}^t \int_x \sigma(x, \tilde{u}(r, x)) \beta'''(\tilde{u}(r, x) - v) \psi(s, y) \rho_{\delta}(x - y) dx dW(r),$$

where $t \geq s - \delta_0$. We now invoke Itô-product rule and obtain

$$J[\beta''', \phi_{\delta, \delta_0}](s; y, v) = - \int_{s-\delta_0}^s \rho'_{\delta_0}(t - s) M_{s-\delta_0}^t[\beta''', \psi, \delta](y, v) dt.$$

Therefore

$$\|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})} \leq \frac{1}{\delta_0} \sup_{s-\delta_0 \leq t \leq s} \|M_{s-\delta_0}^t[\beta'', \psi, \delta](\cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})}.$$

In other words

$$\begin{aligned} & E \left[\sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})} \right] \\ & \leq \frac{1}{\delta_0} E \left[\sup_{0 \leq s \leq T; s-\delta_0 \leq t < s} \|N_t[\beta''', \psi, \delta](\cdot, \cdot) - N_{s-\delta_0}[\beta''', \psi, \delta](\cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})} \right] \end{aligned} \tag{5.21}$$

where

$$N_t[\beta''', \psi, \delta](y, v) = \int_0^t \int_x \sigma(x, \tilde{u}(r, x)) \beta'''(\tilde{u}(r, x) - v) \psi(s, y) \varrho_\delta(x - y) dx dW(r).$$

By a certain modulus of continuity estimate [8, Lemma 4.28, p. 359] for paths of N_t , we have

$$E \left[\sup_{s, t \in [0, T]; |s-t| < \delta_0} \|N_t[\beta''', \psi, \delta](\cdot, \cdot) - N_s[\beta''', \psi, \delta](\cdot, \cdot)\|_\infty^p \right] \leq C \delta_0^a \tag{5.22}$$

for some $a > 0$ and $p > 8$. We combine (5.22) and (5.21) to have

$$E \left[\sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{L^\infty(\mathbb{R} \times \mathbb{R})}^p \right] \leq C \frac{1}{\delta_0^p} \delta_0^a \tag{5.23}$$

for some $a > 0$ and $p > 8$.

Next, we define

$$A_\varepsilon(t) = \int_0^t \varepsilon \|\nabla_y u_\varepsilon(r)\|_2^2.$$

From the moment estimate in Proposition 4.1 we have

$$\sup_{\varepsilon > 0} E[|A_\varepsilon(T)|^p] < \infty, \quad \text{for } p = 1, 2, \dots, T > 0. \tag{5.24}$$

Finally, we now focus on I_2^ε and have

$$|I_2^\varepsilon| \leq E \left[\int_0^T \int_{|y| < C_\psi} \int_{s-\delta_0}^s \sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_\infty \varepsilon |\nabla_y u_\varepsilon(\tau, y)|^2 d\tau dy ds \right]$$

(by Fubini theorem)

$$\begin{aligned}
 &\leq E \left[\sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{\infty} \int_{|y| < C_{\psi}} \int_{\tau=0}^T \left(\int_{s=\tau}^{\tau+\delta_0} \varepsilon |\nabla_y u_{\varepsilon}(\tau, y)|^2 ds \right) d\tau dy \right] \\
 &= \delta_0 E \left[\sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{\infty} \int_{|y| < C_{\psi}} \int_{\tau=0}^T \varepsilon |\nabla_y u_{\varepsilon}(\tau, y)|^2 d\tau dy \right] \\
 &\leq \delta_0 E \left[\sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{\infty} \Lambda_{\varepsilon}(T) \right] \\
 &\quad \text{(by Hölder with } p > 8) \\
 &\leq \delta_0 \left(E \sup_{0 \leq s \leq T} \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_{\infty}^p \right)^{\frac{1}{p}} \left(E[|\Lambda_{\varepsilon}(T)|^q] \right)^{\frac{1}{q}} \\
 &\quad \text{(by (5.23) and (5.24))} \\
 &\leq C \delta_0^{\tilde{a}}, \tag{5.25}
 \end{aligned}$$

for some $\tilde{a} > 0$. In other words, there exists $\tilde{a} > 0$ such that

$$\limsup_{\varepsilon \downarrow 0} |I_2^{\varepsilon}| \leq C(\beta, \psi) \delta_0^{\tilde{a}}$$

and hence

$$A_2(\delta, \delta_0) \rightarrow 0 \quad \text{as } \delta_0 \rightarrow 0. \quad \square \tag{5.26}$$

Finally, we define

$$A_3(\delta, \delta_0) = \limsup_{\varepsilon \downarrow 0} \lim_{l \rightarrow 0} |A_3^{l, \varepsilon}(\delta, \delta_0)| \tag{5.27}$$

Lemma 5.6. *It holds that*

$$A_3(\delta, \delta_0) \rightarrow 0 \quad \text{as } \delta_0 \rightarrow 0.$$

Proof. By integration by parts, we have

$$\begin{aligned}
 &A_3^{l, \varepsilon}(\delta, \delta_0) \\
 &= \frac{1}{2} E \left[\int_{\mathbb{R}} \int_{\Pi_T} J[\beta''', \phi_{\delta, \delta_0}](s; y, v) \left\{ \int_{s-\delta_0}^s \sigma_{\varepsilon}^2(y, u_{\varepsilon}(\tau, y)) \rho_l(u_{\varepsilon}(\tau, y) - v) d\tau \right\} dy ds dv \right].
 \end{aligned}$$

Therefore

$$\begin{aligned}
 |A_3^{l,\varepsilon}(\delta, \delta_0)| &\leq E \left[\int_v \int_0^T \int_{|y| < C_\psi} \int_{s-\delta_0}^s \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_\infty \sigma_\varepsilon^2(y, u_\varepsilon(\tau, y)) \right. \\
 &\quad \left. \times \rho_l(u_\varepsilon(\tau, y) - v) \, d\tau \, dy \, ds \, dv \right] \\
 &= E \left[\int_0^T \int_{|y| < C_\psi} \int_{s-\delta_0}^s \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_\infty \sigma_\varepsilon^2(y, u_\varepsilon(\tau, y)) \, d\tau \, dy \, ds \right] \\
 &\leq E \left[\int_0^T \int_{|y| < C_\psi} \int_{s-\delta_0}^s \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_\infty g^2(y) (1 + |u_\varepsilon(\tau, y)|^2) \, d\tau \, dy \, ds \right] \\
 &\leq C \int_0^T \int_{s-\delta_0}^s (E \|J[\beta''', \phi_{\delta, \delta_0}](s; \cdot, \cdot)\|_\infty^2)^{\frac{1}{2}} \\
 &\quad \times \left(E \int_{|y| < C_\psi} g^4(y) (1 + |u_\varepsilon(\tau, y)|^4) \, dy \right)^{\frac{1}{2}} \, d\tau \, ds \\
 &\leq \frac{C(\beta, \psi)}{\delta_0^{\frac{3}{4}}} \int_0^T \int_{s-\delta_0}^s (1 + E \|u_\varepsilon(\tau)\|_4^4)^{\frac{1}{2}} \, d\tau \, ds \\
 &\leq C(\beta, \psi) \delta_0^{\frac{1}{4}} T \left[1 + \sup_{\varepsilon > 0} \sup_{0 \leq t \leq T} E \|u_\varepsilon(t, \cdot)\|_4^4 \right]^{\frac{1}{2}}. \tag{5.28}
 \end{aligned}$$

Thus

$$\limsup_{\varepsilon \downarrow 0} \lim_{l \rightarrow 0} |A_3^{l,\varepsilon}(\delta, \delta_0)| \leq C(\beta, \psi, T) \delta_0^{\frac{1}{4}}$$

and hence $A_3(\delta, \delta_0)$ has the desired property. \square

Lemma 5.7. *It holds that*

$$\begin{aligned}
 \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} B^{\varepsilon, l}(\delta, \delta_0) &= -E \left[\int_{H_T} \int_{H_T} \sigma(x, \tilde{u}(r, x)) \sigma(y, v(r, y)) \beta''(\tilde{u}(r, x) - v(r, y)) \right. \\
 &\quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) \, dr \, dx \, dy \, ds \right] \tag{5.29}
 \end{aligned}$$

Proof. Since $\|\beta''(\cdot)\|_\infty < \infty$, we can use dominated convergence theorem and conclude

$$\begin{aligned} \lim_{l \rightarrow 0} B^{\varepsilon, l}(\delta, \delta_0) &= -E \left[\int_{\Pi_T} \int_x \int_{s-\delta_0}^s \beta''(\tilde{u}(r, x) - u_\varepsilon(r, y)) \sigma(x, \tilde{u}(r, x)) \sigma_\varepsilon(y, u_\varepsilon(r, y)) \right. \\ &\quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] \\ &= -E \left[\int_{\Pi_T} \int_{\Pi_T} \beta''(\tilde{u}(r, x) - u_\varepsilon(r, y)) \sigma(x, \tilde{u}(r, x)) \sigma_\varepsilon(y, u_\varepsilon(r, y)) \right. \\ &\quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] \tag{5.30} \end{aligned}$$

We use the uniform integrability conditions along with approximation properties of σ_ε and pass to the limit $\varepsilon \downarrow 0$ to obtain

$$\begin{aligned} \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} B^{\varepsilon, l}(\delta, \delta_0) &= -E \left[\int_{\Pi_T} \int_{\Pi_T} \sigma(x, \tilde{u}(r, x)) \sigma(y, v(r, y)) \beta''(\tilde{u}(r, x) - v(r, y)) \right. \\ &\quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right]. \quad \square \end{aligned}$$

We can now finally wrap up the proof of [Lemma 5.1](#).

Proof of Lemma 5.1. We now simply choose $A(\delta, \delta_0) = A_1(\delta, \delta_0) + A_2(\delta, \delta_0) + A_3(\delta, \delta_0)$. Note that, in view of [\(5.7\)](#),

$$\begin{aligned} &E \left[\int_0^T \int_y \int_0^T \int_x \sigma(x, \tilde{u}(r, x)) \beta'(\tilde{u}(r, x) - v) \phi_{\delta, \delta_0}(r, x, s, y) dx dW(r) \Big|_{v=v(s, y)} dy ds \right] \\ &= \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} E[Z_{\varepsilon, \delta, \delta_0, l}] \\ &= \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} [A_1^{\varepsilon, l} + A_2^{\varepsilon, l} + A_3^{\varepsilon, l} + B^{\varepsilon, l}(\delta, \delta_0)] \\ &\leq \lim_{\varepsilon \downarrow 0} \sup \lim_{l \downarrow 0} |A_1^{\varepsilon, l}(\delta, \delta_0)| + \lim_{\varepsilon \downarrow 0} \sup \lim_{l \downarrow 0} |A_2^{\varepsilon, l}(\delta, \delta_0)| \\ &\quad + \lim_{\varepsilon \downarrow 0} \sup \lim_{l \downarrow 0} |A_3^{\varepsilon, l}(\delta, \delta_0)| + \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} B^{\varepsilon, l} \\ &= A_1(\delta, \delta_0) + A_2(\delta, \delta_0) + A_3(\delta, \delta_0) + \lim_{\varepsilon \downarrow 0} \lim_{l \downarrow 0} B^{\varepsilon, l} \\ &= A(\delta, \delta_0) - E \left[\int_{\Pi_T} \int_{\Pi_T} \sigma(x, \tilde{u}(r, x)) \sigma(y, v(r, y)) \beta''(\tilde{u}(r, x) - v(r, y)) \right. \\ &\quad \left. \times \phi_{\delta, \delta_0}(r, x, s, y) dr dx dy ds \right] \end{aligned}$$

where we have used Lemma 5.7. Furthermore, by Lemmas 5.4–5.6, the function $A(\delta, \delta_0)$ has the desired property as $\delta_0 \rightarrow 0$. \square

We have seen from Lemma 4.8 that $v(t, x) = \bar{u}(t, x)$ is a stochastic entropy solution. Moreover, we conclude from Lemma 5.1 that $\bar{u}(t, x)$ is indeed a stochastic strong entropy solution of (1.1)–(1.2), which completes the proof of Theorem 2.3.

6. A critique on the strong-in-time formulation

In this final section, we will contest the suitability of strong-in-time formulation of [8] and try to make a case for weak-in-time formulation. However, the issues that we are going to raise are purely technical in nature and do not any way disturb the broader message of [8]. We could not have emphasized more on the fact the article [8] is no less than a milestone in the area.

For any L^p -valued solution process $u(\cdot, x)$ with continuous sample paths, it is easy to see that the strong-in-time and weak-in-time formulations are equivalent to each other. Furthermore, if it is not established that the solution process has continuous paths then weak-in-time formulation is certainly a more appropriate way to move forward. Just as in the deterministic case, the authors use vanishing viscosity method for existence in [8] and attempts have been made in [8] to justify that the vanishing viscosity limit has continuous sample paths when treated as an \mathcal{M}_0 -valued process. To be more precise, it is shown in [8, Lemma 4.23, p. 355] that

$$\lim_{t \downarrow s} E[r(\mu_0(t), \mu_0(s))] = 0, \quad (6.1)$$

and a claim has been made that (6.1) implies that $\mu_0(\cdot)$ has continuous sample paths as \mathcal{M}_0 valued process. We strongly disagree with the derivation of (6.1) in the proof of [8, Lemma 4.23, p. 355]. Moreover, the claim that $\mu_0(\cdot)$ has continuous sample paths because of (6.1) is also wrong. In fact, we make a counter claim that an estimate of type (6.1) may not imply path continuity. To see this, let N_t be the usual Poisson process with parameter $\lambda > 0$. Then

$$\lim_{t \rightarrow s} E[d_{\mathbb{R}}(N_t, N_s)] = \lim_{t \rightarrow s} E[|N_t - N_s|] = \lim_{t \rightarrow s} \lambda |t - s| = 0, \quad (6.2)$$

but N_t clearly does not have continuous sample paths. Therefore, $\mu_0(\cdot)$ cannot be claimed to have continuous sample paths on the basis of (6.1) alone. This invalidates the claim in [8, Lemma 4.22, p. 355] that $\mu_0(t)$ has trajectories in $C([0, \infty), \mathcal{M}_0)$, and puts a question mark next the entropy inequality [8, (74), p. 355].

Moreover, the proof (6.1) in [8, Lemma 4.23, p. 355] is incorrect due to the lapses in [8, Lemma 4.15, p. 343]. To elaborate on this point, let us look at the proof [8, Lemma 4.15, p. 343] where it is shown that

$$\lim_{\varepsilon \downarrow 0} E[d(\mu_\varepsilon(\cdot), \mu_0(\cdot))] = \lim_{\varepsilon \downarrow 0} \int_0^\infty e^{-t} E[\min(1, r(\mu_\varepsilon(t), \mu_0(t)))] dt = 0. \quad (6.3)$$

Clearly, (6.3) only implies that $\lim_{\varepsilon \downarrow 0} E[r(\mu_\varepsilon(t), \mu_0(t))] = 0$ **for almost every** $t \geq 0$, contrary to the claim in [8, Lemma 4.15, p. 343] that $\lim_{\varepsilon \downarrow 0} E[r(\mu_\varepsilon(t), \mu_0(t))] = 0$ **for every** $t \geq 0$. This jeopardizes the claim that

$$\lim_{\varepsilon \downarrow 0} (\mu_\varepsilon(t_1), \dots, \mu_\varepsilon(t_m)) = (\mu_0(t_1), \dots, \mu_0(t_m)) \quad \text{in probability}$$

for each $0 \leq t_1 \leq \dots \leq t_m$. We object to the wording ‘for each $0 \leq t_1 \leq \dots \leq t_m$ ’. In our view, the correct wording should be ‘ $0 \leq t_1 \leq \dots \leq t_m$ where t_i ’s are chosen from a set of full Lebesgue measure in $[0, \infty)$ ’. Hence, one would only be allowed to pass to the limit in ε in [8, (73), p. 354] for **almost every** $(t, s) \in [0, \infty) \times [0, \infty)$, and [8, (74), p. 355] would be valid only for almost every $(t, s) \in [0, \infty) \times [0, \infty)$.

Therefore, it is fair to say that the vanishing viscosity limit does not have sufficiently clear point-wise picture in time for its paths, and it is worthwhile to go for the weak-in-time entropy formulation for (1.1). It is worth mentioning that it may well be possible to prove the path continuity for the entropy solution, but the methods of [8] are not adequate for that. Also, the weak-in-time formulation has an immediate correspondence with kinetic formulation of [5]. Though the model that is considered in [5] deals with periodic solutions, kinetic solutions are claimed to have continuous paths. It may be possible to develop kinetic solution framework in a general case, which might help to establish path continuity for our framework.

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